

Drone RGB and Multispectral Data Processing Protocol

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Abbreviations

CRP	Calibrated Reflectance Panel
DJI	SZ DJI Technology Co., Ltd.
GCP	Ground Control Point
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
RGB	Red, Green, Blue
RTK	Real Time Kinematic
UAS	Unoccupied Aircraft System

Scope

This document describes the UAS data processing workflow developed for RGB and multispectral imagery for simultaneously collected on Matrice 300 (M300) RTK platform. The workflows outlined in this document are designed for use with RGB imagery acquired with DJI Zenmuse P1 camera and multispectral imagery from MicaSense RedEdge-MX or Dual sensors (Drone Data Collection Protocol). The M300 is equipped with GNSS RTK (Global Navigation Satellite System Real Time Kinematic) which can be used with the D-RTK 2 base station to determine the position of the UAS with centimetre-level accuracy. This enables high georeferencing accuracy without the use of ground control points (GCPs) or ground surveys. This protocol describes two approaches to processing RGB and multispectral imagery using Agisoft Metashape Pro:

1. Automated processing using a Python workflow
 - The workflow is described in 'Summary of processing workflow using Agisoft Metashape'.
 - User input is required to select images for MicaSense reflectance calibration.
 - Equivalent Metashape toolbar commands are listed for all steps.
 - A prototype to create a custom widget in Agisoft Metashape for the same workflow is described in 'Appendix 5: Processing workflow using a custom Metashape window'.
2. Step-by-step workflow using the Metashape graphical user interface (GUI)

The primary data products from this workflow are co-registered RGB and multispectral orthomosaics.

Summary of processing workflow using Agisoft Metashape

Table 1: Summary of automated processing workflow on Agisoft Metashape Pro

#	Chunk	Processing Step	Metashape Menu	Summary
1	N/A	Metashape Preferences	Tools -> Preferences	General: Update 'Theme' to Classic Advanced <ul style="list-style-type: none"> Select 'Keep key points' 'Strip file extensions from camera labels'
2	N/A	Save Metashape project as .psx file	File -> Save As	Suggested naming: 'YYYYMMDD_ PlotName.psx' (YYYYMMDD – date of data collection). Save project in imagery/metashape/ within the TERN plot folder.
Run script to add RGB and multispectral imagery and to start the processing workflow. See Table 2 for steps completed in the script.				
3	N/A	Process rgb and multispec chunks to generate orthomosaic tiff	Tools -> Run Script	<p>Note: One-time setup required to install extension python packages listed in 'Agisoft Metashape setup'.</p> <p>Script name: metashape_proc.py Required argument: -crs "EPSG code for target projected coordinate system" (Find the EPSG code of the coordinate system.)</p> <p>Optional arguments (see 'Appendix 1: Note on Folder Structure' for information on default path arguments)</p> <ol style="list-style-type: none"> -multispec "path to multispec image folder" Default is relative to project location: ../multispec/level0_raw/ -rgb <path to p1 images" Default is relative to project location: ../rgb/level0_raw/ Strength value to smooth P1 model. "-smooth <low/medium/high>". Default is low. Low: for low-lying vegetation (grasslands, shrublands), Medium and high: as appropriate for forested sites. If blockshift of p1 coordinates required (see following sections for details): --blockshift_p1 If blockshift enabled: -drtk "path to txt file with DRTK cords" Default is relative to project location: .././drtk/drtk_australian_cartesian.txt <p>Outputs/intermediate files and location:</p> <ol style="list-style-type: none"> P1 orthomosaic tiff (imagery/rgb/level1_proc/) MicaSense orthomosaic (imagery/multispec/level1_proc/) CSV of updated positions for p1 (if blockshifted) and micasense (imagery/metashape/) Smoothed P1 model used as orthorectification surface for both p1 and micasense (imagery/metashape/)
Script paused for user to complete the following steps				
4	multispec	Locate panels	Select 'multispec' chunk in Workspace pane. Tools -> Calibrate Reflectance	<ul style="list-style-type: none"> Click 'Locate Panels' to move images of MicaSense calibration Panel to camera group 'Calibration Images' and to automatically set the panel mask. After images have been identified, press 'Cancel'. Panel mask must be inspected before reflectance calibration.
5	multispec	Expand 'Calibration images' folder under 'Cameras'	NA	<ul style="list-style-type: none"> On the Workspace pane, inspect images in 'Calibration Images' to identify images to be used (from either before or after flight). Select images that are not to be used for calibration. Right-click and 'Remove Cameras'. Open a calibration image. Click on the 'Show Masks' icon. Only the panel must be unmasked. If the default mask is not set correctly, fix it manually as follows: <ul style="list-style-type: none"> Click on 'Rectangle selection', right click on calibration image in the main window, 'Reset Mask', select panel area using 'Rectangle selection', 'Add Selection'. This will set the panel area to be masked. Now select 'Invert Mask'. Repeat this for other channels (change the channel displayed using Tools -> Set Primary Channel). Repeat for all images.
6	Click on 'Resume Processing' in the toolbar to complete the processing workflow. See Table 2 for more information.			

Table 2: Summary of steps completed in Python script metashape_proc.py and equivalent commands on Metashape GUI.

Chunk	Processing step	Equivalent step on Metashape GUI	Summary
NA	Add Chunk	Workspace pane	Right-click and select 'Add Chunk' and rename as 'rgb'
rgb	Add images	Workflow -> Add Folder	Navigate to folder containing images and select all images to be added. Select 'Single cameras'
NA	Add Chunk	Workspace pane	Right-click and select 'Add Chunk' and rename as 'multispec'
multispec	Add images	Workflow -> Add Folder	First double click on multispec chunk to make it active. Select toolbar command and navigate to folder (with subfolders) of all MicaSense images. In the next dialog, select 'Multi-camera system' option.
multispec	Locate panels, Select Calibration images	Tools -> Calibrate Reflectance	User input to select micasense calibration images (Table 1)
rgb	If blockshift enabled	Update P1 Camera positions	Calculate difference between D-RTK2 base station position recorded on field and that from AUSPOS. Apply difference to all cameras. Convert CRS to target projected CRS. Save shifted_p1_pos.csv in project folder.
	Estimate Image Quality	Photos pane – context menu	Estimate Image Quality from the context menu. Remove Images with Quality < 0.7 (Hardcoded value).
	Camera calibration	Tools -> Camera calibration	Lever-arm offsets (m) for p1 from single gimbal position: 0.087, 0.0, 0.0 (m) (Under GPS/INS Offset, 'Enable Reference' under Reference Column, and enter above values for X, Y, Z).
	Set camera accuracy	Reference pane - Settings	Under 'Measurement Accuracy' set Camera accuracy (m) to 0.1 m
	Align Photos	Workflow -> Align Photos	Settings - Accuracy: High, Generic preselection – unchecked, Reference preselection: Source.
	Optimise alignment	Reference pane – Optimize Cameras	Default settings (Following are unchecked: Fit b1, b2, k4 & all Advanced)
	Build dense cloud	Workflow -> Build Dense Cloud	Set Quality: Medium, Depth Filtering: Mild.
	Build Mesh	Workflow -> Build Mesh	Set Source data: Dense cloud, Surface type: Height field, Face count: Medium.
	Decimate mesh	Tools->Mesh->Decimate Mesh	Decimate model to half of original face count.
	Smooth mesh	Tools -> Mesh -> Smooth Mesh	Strength: 50 (low), 100 (medium), 200 (high). Note that settings are yet to be tested in sites with complex/dense vegetation.
	Export Model	Workspace pane – 3D Model context menu	Export model – necessary so that it can be used as surface for multispec chunk. Model exported in target CRS. Naming: <proj_name> _rgb_smooth_<strength_value>.obj
	Build orthomosaic	Workflow -> Build Orthomosaic	Set Surface: Mesh. Refine seamlines: True.
Export orthomosaic	Workspace pane – Orthomosaic context menu	Pixel size rounded to 2 decimal places. Big Tiff, Tiled, overviews enabled. Naming: <proj_name>_rgb_ortho_<resolution_in_m>.tif	

Chunk	Processing step	Equivalent step on Metashape GUI	<p style="text-align: center;">Summary</p> <p>For more information on Metashape commands refer to the Metashape Pro User Manual (Agisoft 2022a)</p>
multispec	Interpolate micasense image position	Tools->Run Script (script: Metashape_upd_cam_pos_only.py. See 'Interpolate MicaSense camera positions')	Micasense and p1 mage timestamps used to interpolate micasense camera position. Save updated micasense positions in interpolated_micasense_pos.csv in project folder. Remove cameras that triggered outside flight area. Load updated camera positions in chunk.
	Camera Calibration	Tools -> Camera calibration	Lever-arm offsets (m) for MicaSense sensor (in Gimbal 2) from single gimbal position: RedEdge-MX: -0.097, -0.03, -0.06 MicaSense Dual: -0.097, 0.02, -0.08
	Set camera accuracy	Reference pane - Settings	Under 'Measurement Accuracy' set Camera accuracy (m) to 0.1 m
	Estimate Image Quality	Photos pane – context menu	Estimate Image Quality from the context menu. Remove Images with Quality < 0.7 (Hardcoded value).
	Set Primary Channel Set Brightness	Tools -> Set Primary Channel Tools-> Set Brightness	Set NIR as Primary Channel. Set optimal Brightness values for better display of images.
	Raster transform	Tools -> Set Raster Transform	Relative reflectance values, B1 is B1/32768 for band 1 and repeat for all bands.
	Reflectance Calibration	Tools -> Calibrate Reflectance	Check 'Use reflectance panels' and 'Use sun sensor'. Click OK.
	Align Photos	Workflow -> Align Photos	Settings - Accuracy: High, Generic preselection – unchecked, Reference preselection: Source.
	Optimise alignment	Reference pane – Optimize Cameras	Default settings. (Following are unchecked: Fit b1, b2, k4 & all Advanced)
	Build dense cloud	Workflow -> Build Dense Cloud	Set Quality: Medium, Depth Filtering: Mild.
	Import Model	File -> Import -> Import Model	Import p1 model created earlier. Import model in the target CRS (was exported likewise).
	Build orthomosaic	Workflow -> Build Orthomosaic	Set Surface: Mesh. Refine seamlines: True.
Export orthomosaic	Workspace pane – Orthomosaic context menu	Pixel size rounded to 2 decimal places. Big Tiff, Tiled, overviews enabled. Naming: <proj_name>_multispec_ortho_<resolution_in_m>.tif	

Agisoft Metashape setup

Update Preferences

1. Open Agisoft Metashape Pro. Access Tools → Preferences.
2. In the General tab, update Theme to 'Classic'. Select 'Write log to file' and browse to enter the path and a name for the .txt file.

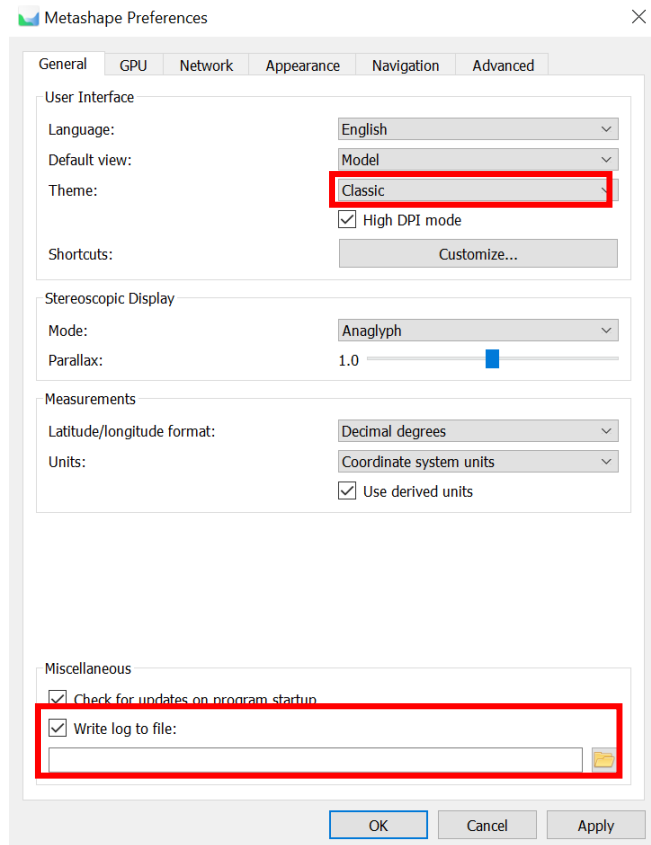


Figure 1: Update Metashape Preferences. Select theme 'Classic' for display to match the screenshots in this document. Choose a path to save the log file.

3. In the GPU tab, make sure all GPUs are selected. Uncheck the box 'Use CPU when performing GPU accelerated processing'.

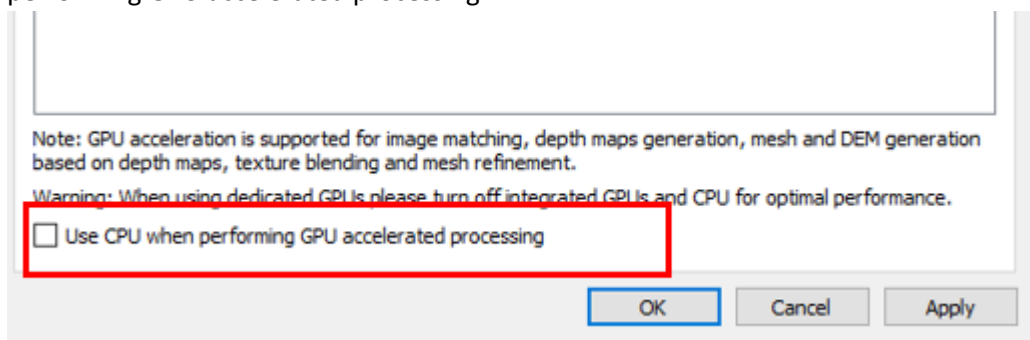


Figure 2: When using dedicated GPUs disable integrated CPU and GPUs. In the GPU tab, disable the option 'Use CPU...' as shown above.

4. In the Advanced tab, ensure that 'Keep depth maps' and 'Strip file extensions from camera labels' are checked. Under Miscellaneous, select 'Enable rich Python console'.

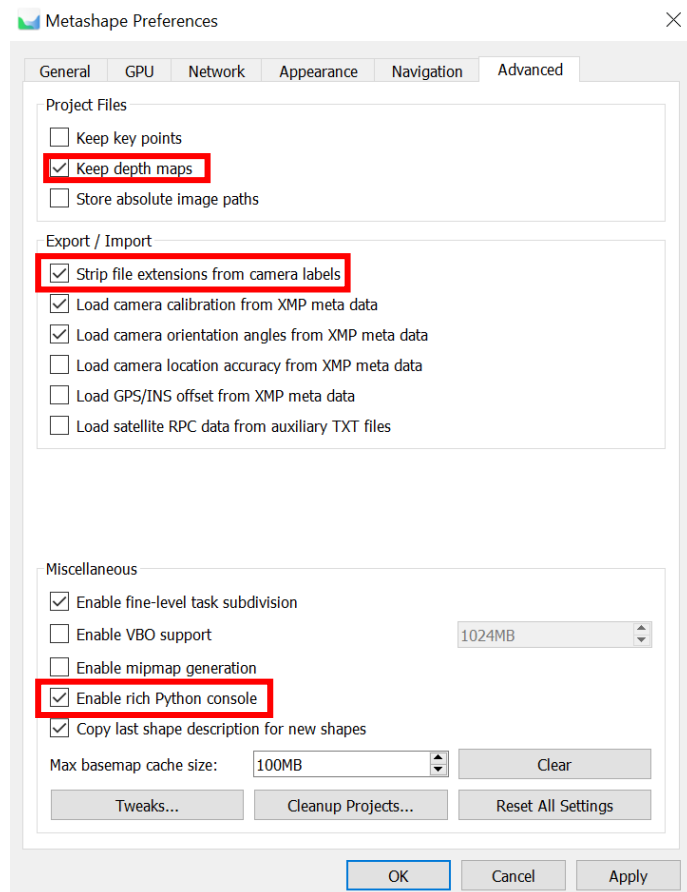


Figure 3: Update Advanced Preferences. The settings to be updated are highlighted above.

Install external packages

The Python scripts described in this protocol use site packages (exifread, numpy, pyproj) that must first be installed in Metashape.

Open a Command window (cmd) and install each package using:

```
"<path to metashape pro>\python\python.exe" -m pip install  
<package_name>
```

Example:

```
"C:\Program Files\Agisoft\Metashape Pro\python\python.exe" -m  
pip install exifread numpy pyproj
```

Automated processing workflow

Python script `metashape_proc.py` is used to run the Structure from Motion workflow on the P1 and MicaSense imagery and generate co-registered orthomosaic tiff files (Table 1 and Table 2).

Arguments and default values for the script `metashape_proc.py` are shown in Table 3.

Table 3: Arguments and default values used in the Python workflow `metashape_proc.py`

Argument Type	Argument	Value	Default
Required	-crs	EPSG code of output projected coordinate reference system. Find the EPSG code of the required coordinate system.	NA
Optional	-multispec	Path to multispectral images level0_raw folder	Relative to project location: ../multispec/level0_raw
	-rgb	Path to RGB level0_raw folder containing the MRK files	Relative to project location: ../rgb/level0_raw/
	-smooth	Strength value to smooth the RGB 3D model. Select one of low, medium or high as appropriate for the vegetation on site. For more information see notes below and examples in 'Appendix 2: Setting the smoothing strength value'.	Low
	--blockshift_p1	Use when P1 image coordinates are to be blockshifted using AUSPOS result for D-RTK2 base station coordinates. Note the double dash in this argument. It is a 'store true' argument.	NA
	-drtk	If blockshift enabled, txt file containing field and AUSPOS Cartesian coordinates for DRTK (See 'Appendix 3: Process D-RTK2 base station data').	Relative to project location: ../drtk/drtk_auspos_cartesian.txt

Table 4: Example Arguments for metashape_proc.py

Arguments	Interpretation
-crs "7855"	Use GDA2020 MGA Zone 55 as output projected CRS. Use defaults for image folder locations, smoothing strength. No blockshift.
-p1 "G:\SASMDD0009\20220517\imagery\rgb\level0_raw\test" rgb "G:\SASMDD0009\20220517\imagery\multispec\level0_raw\test" -crs "7854"	Use input paths as specified for p1 and micasense. Use GDA2020 MGA Zone 54 as output projected CRS. No blockshift.
-crs "7855" --blockshift_p1	Use GDA2020 MGA Zone 55 as output projected CRS. Use defaults for image folder locations, smoothing strength. Blockshift, use default location for drtk txt file.

Setting the Strength value to smooth the P1 3D model

Orthomosaics can be built using either a digital elevation model (DEM) or a mesh generated from the 3D point cloud. The methods and parameters used depend on the complexity of vegetation, and the purpose of the orthomosaic (e.g., is geometric accuracy of trees in the orthomosaic important for the analysis, or should the trees look 'aesthetically pleasing?'). Further testing is required to establish optimal settings for different environments. Here a polygonal mesh (3D model) is generated from the dense cloud, decimated, and smoothed to remove artefacts (e.g., on the edges between tree crowns and ground in complex vegetated environments). This smoothed surface generated from the RGB model is used as the projection surface for both RGB and multispectral imagery. See 'Appendix 2: Setting the smoothing strength value' for examples of models of different sites generated with varying smoothing strengths.

- Strength values are 50, 100, 200 respectively for low/medium/high
- low: for low-lying vegetation (grasslands, shrublands)
- medium or high: as appropriate for forested sites

Run Script

1. Open Agisoft Metashape Pro. Save project in format 'YYYYMMDD_ PlotName.psx' where YYYYMMDD is the date of data acquisition and PlotName is the name of TERN plot. *Example: 20211012_SASRIV0001.psx.*
2. Switch to the 'Console' tab to view progress of the script.
3. Select **Tools -> Run Script (Ctrl+R)**. Under '**Script**', navigate to the location of the M300 Python scripts and select metashape_proc.py.
4. Under '**Arguments**', enter the arguments as necessary **noting that the -crs is a required argument**. See Table 3 for a list of arguments and default values. All argument values must be in double quotes "". Click OK.

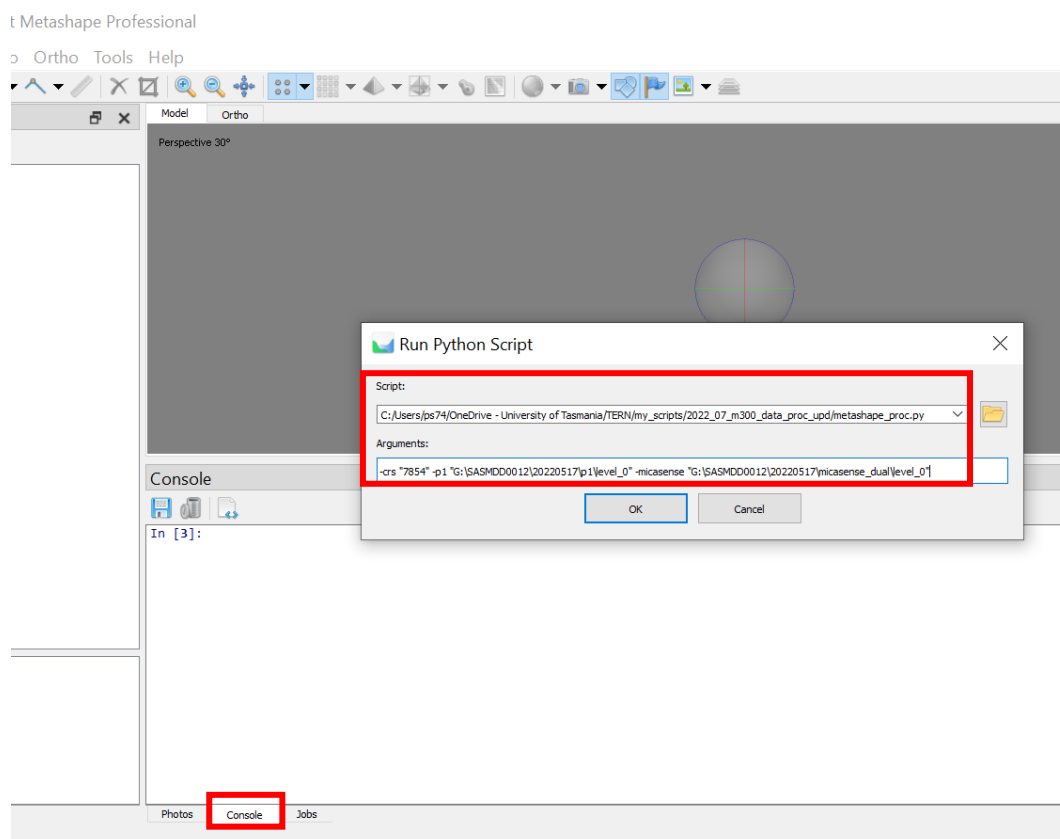


Figure 4: Automated Python workflow: use Tools-> Run Script to run metashape_proc.py. Enter Arguments as required and select OK.

5. Monitor progress through the Progress Dialog and the Console tab.

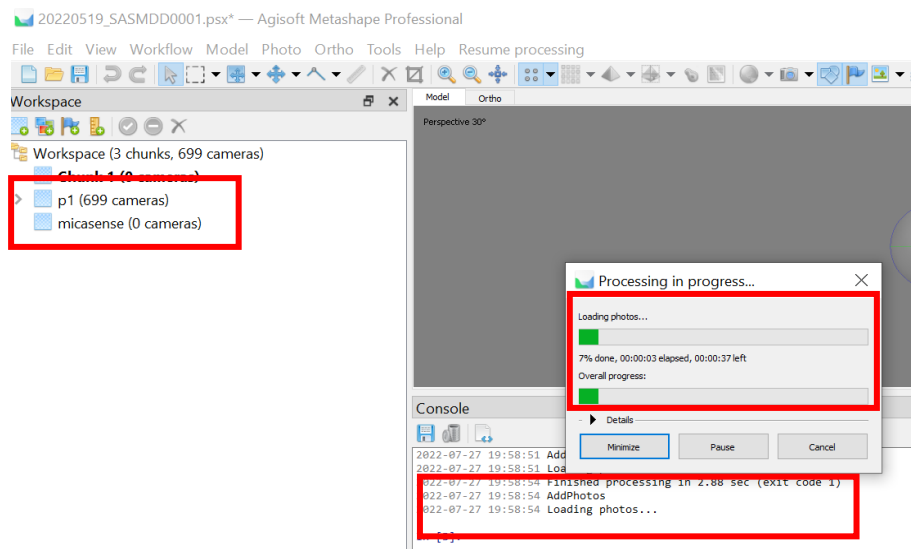


Figure 5: Monitor progress using the Console tab. In the Workspace pane above note that the p1 and micasense chunk creation is in progress.

6. When the rgb and multispec chunks are created, the script will be paused for user input on Calibration Images for the multispectral data. Select OK on the dialog that appears. The following section goes over the steps to locate the calibrated reflectance panel (CRP) and select calibration images for the multispectral imagery.

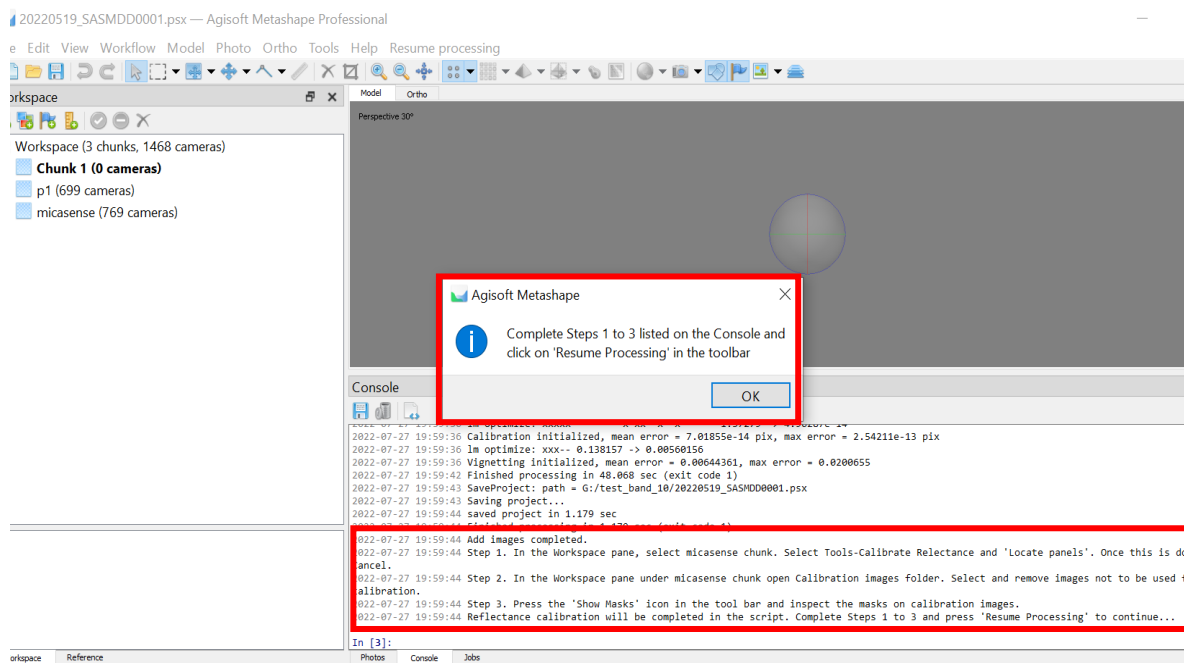


Figure 6: After the images are added, the script is paused for user input on micasense calibration. The steps to be completed are listed on the Console tab.

MicaSense: Select calibration images

Calibration images must be located and selected for calibration by the user. However, note that reflectance calibration will be completed (using both the panel and the sun sensor) later within the Python workflow.

(Note that some of the following screenshots are from 10-band MicaSense Dual sensor and hence may look different to what is displayed for 5-band RedEdge-MX.)

7. Select Tools -> Calibrate Reflectance. Select 'Locate panels'. **This step is necessary even if calibration images have been automatically moved to the Calibration Images group.**

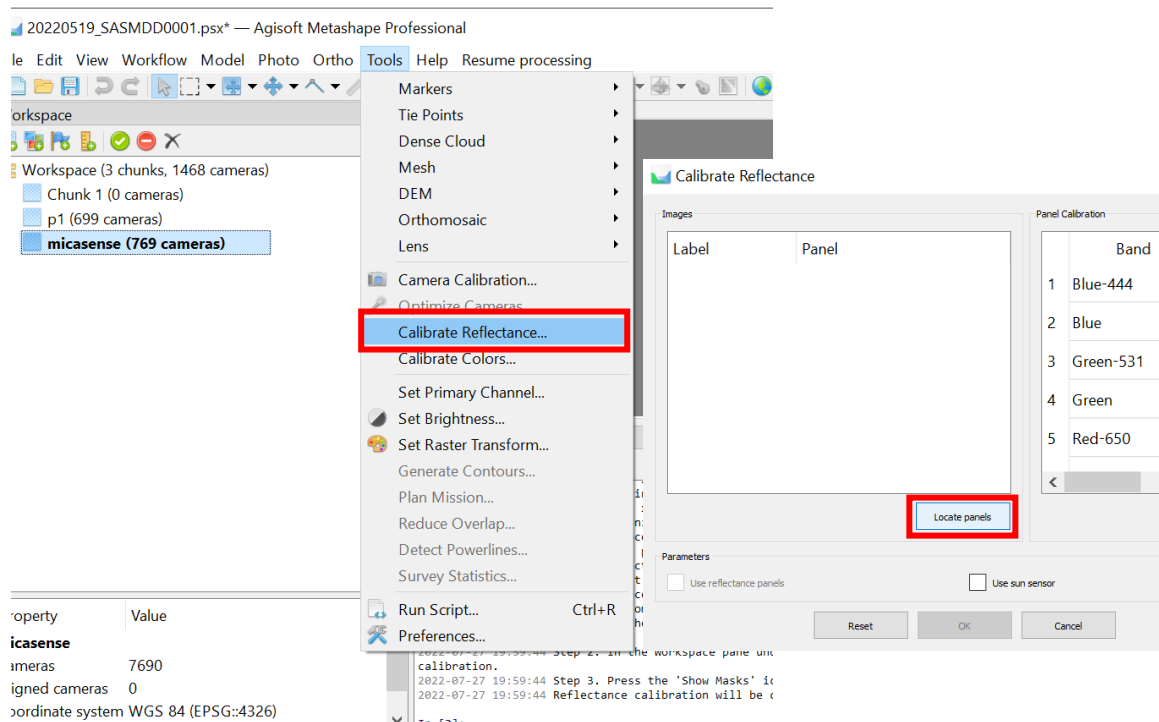


Figure 7: Use Tools -> Calibrate Reflectance and select Locate panels

8. When the 'Locate panels' step is complete, check that the 'Panel' is the CRP model that was used in the field (look for the right serial number 'RP06...'). The first time this is done, the csv of the calibration panel might have to be loaded (from local drive or contact [MicaSense](#)).
9. Click 'Cancel'. Reflectance calibration will be completed in the script. Next, panel masks must be checked, and calibration images chosen from either pre or post flight.

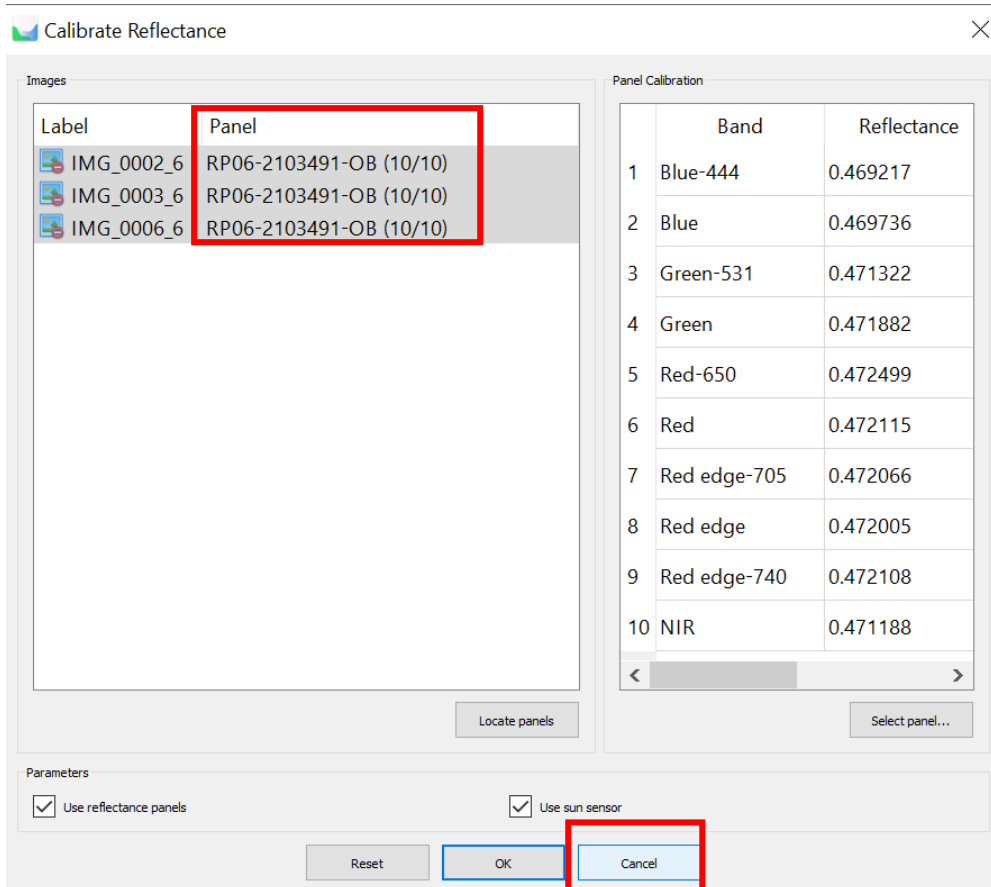


Figure 8: When the panel/images have been located, press Cancel.

10. In the Workspace pane, navigate to the Calibration Images group within multispec chunk. Inspect the photos and identify the ones to use for reflectance calibration.

- **These images must be sharp and without shadows on the panel.**
- Check that the entire panel is covered in the image. (If it is not, remove the image by using the context menu and 'Remove Camera').

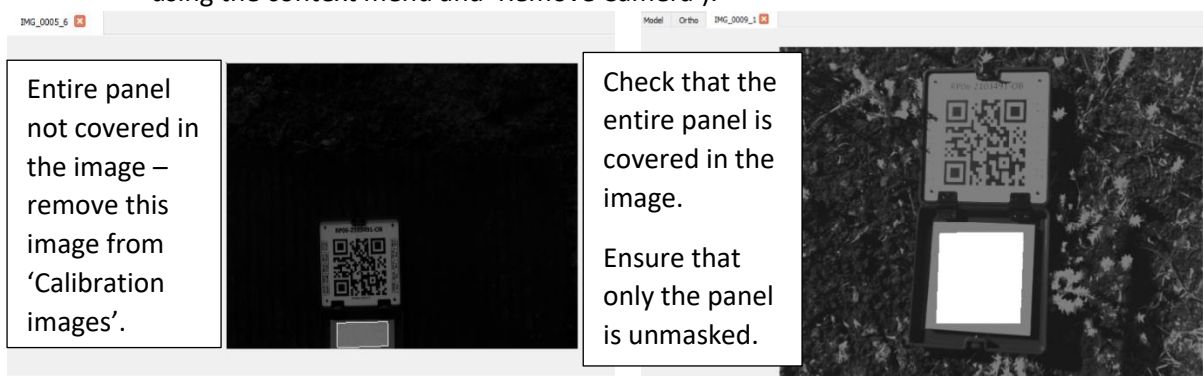


Figure 9: Open calibration images from the folder in multispec chunk to choose images from either pre or post flight. Select images where the entire panel is covered.

- Click on '**Show Masks**' in the photo menu (Figure 10) and inspect the mask set by default. Only the panel must be unmasked.
 - If the default mask is not set correctly, fix it manually: in the Photo menu, click on 'Rectangle selection'. Right click on calibration image in the main window, 'Reset Mask', select panel area using 'Rectangle selection', 'Add Selection'. This will set the

panel area to be masked. Now select 'Invert Mask'. Repeat for all channels of all images to be fixed.

- Repeat this for other channels (change the channel displayed using Tools -> Set Primary Channel). Repeat for other images.

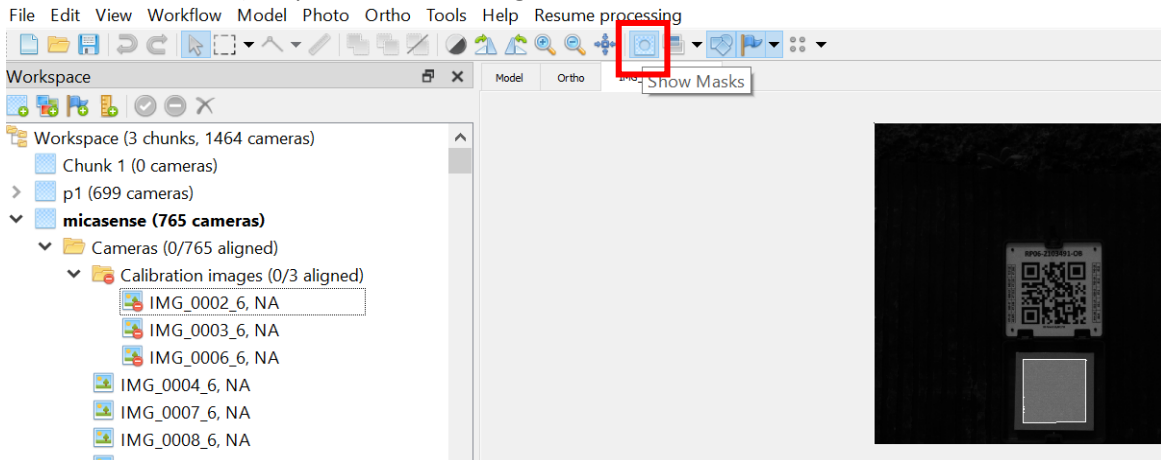


Figure 10: Use the 'Show Masks' icon to inspect the default mask set for the calibration images.

11. Using the above steps identify images taken at a time (either from before or after flight) that best represent the illumination condition during the flight. Finally, in the Workspace pane select images that will not be used for calibration and right-click to 'Remove Cameras'.

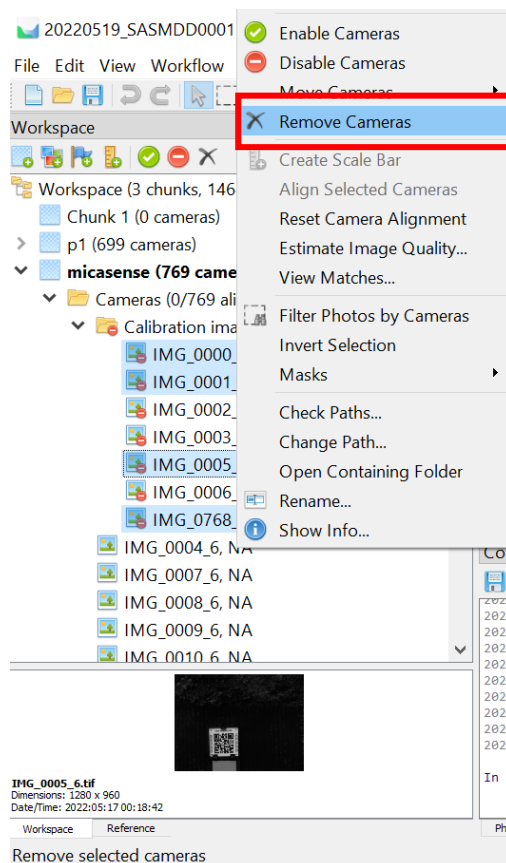


Figure 11: Remove cameras that are not to be used for calibration.

Resume processing

12. Click on the 'Resume Processing' button on the toolbar to complete the processing workflow.

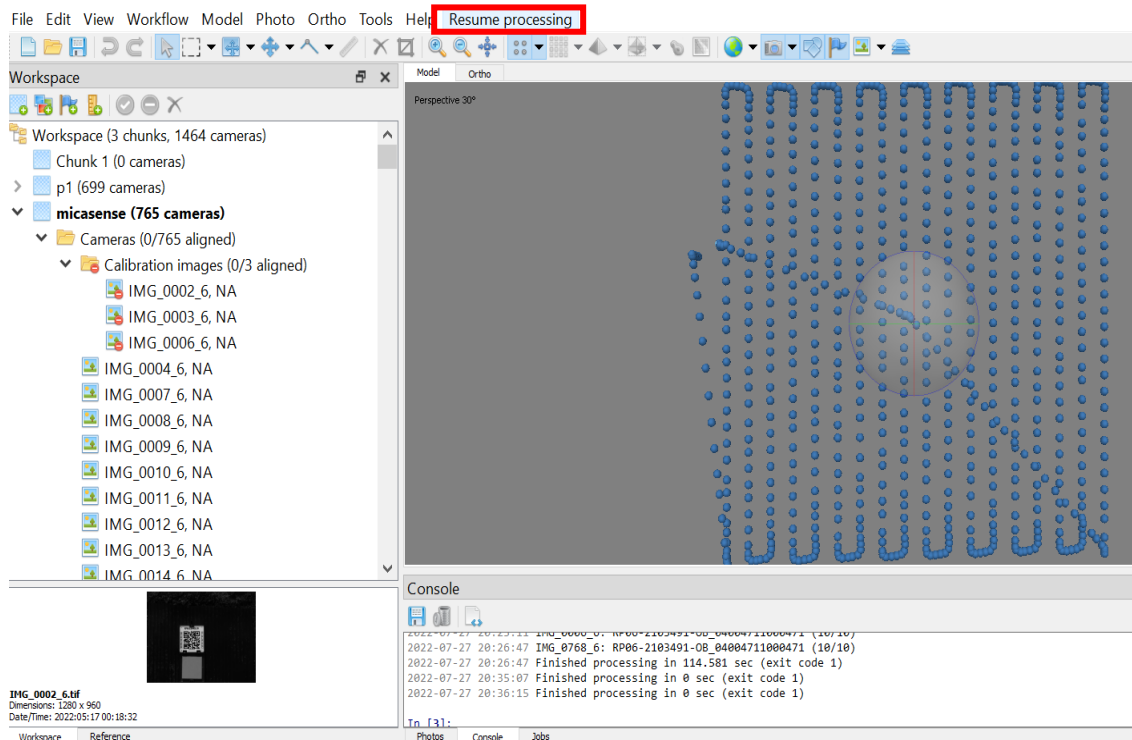


Figure 12: Click on 'Resume processing' in the toolbar to complete the automated workflow.

13. Progress will be displayed on the Metashape progress dialog.

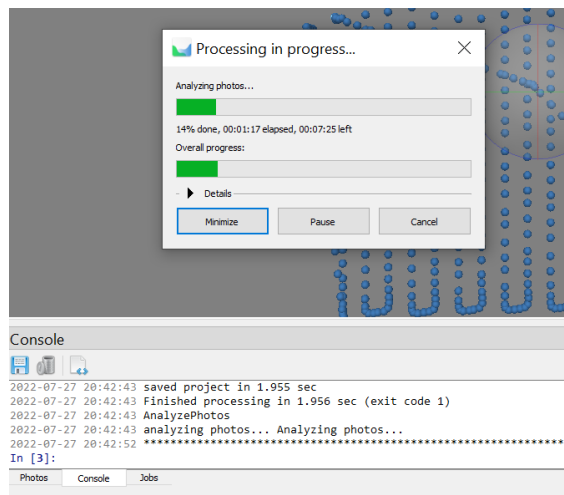


Figure 13: Script progress displayed in the progress dialog and on the Console tab.

14. The remaining steps are completed in the order listed in Table 2. As an estimate of the processing times, processing the rgb chunk for a 150 m x 150 m plot takes around 6 hours and multispec chunk around 3 hours. Workstation specs: 8 core intel i9-11900 2.5 GHz, 16 GB dedicated graphics memory (NVIDIA Quadro RTX5000), 2 TB SSD, 128 GB RAM.
15. When the processing is complete, the RGB and multispectral orthomosaic tif are saved in the <sensor>/level1_proc/ folders. If rgb/ and multispec/ folders are not found, files are saved in the project folder. Intermediate files are also saved in the project folder.

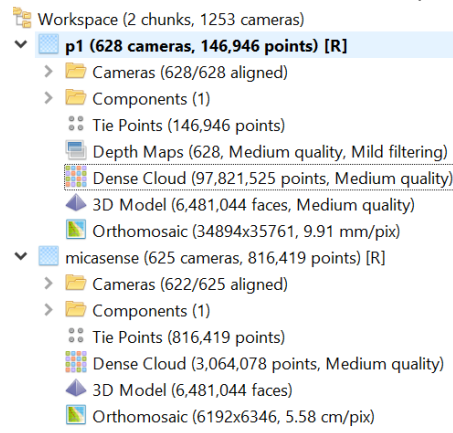


Figure 14: Workspace pane when p1 and micasense processing is complete.

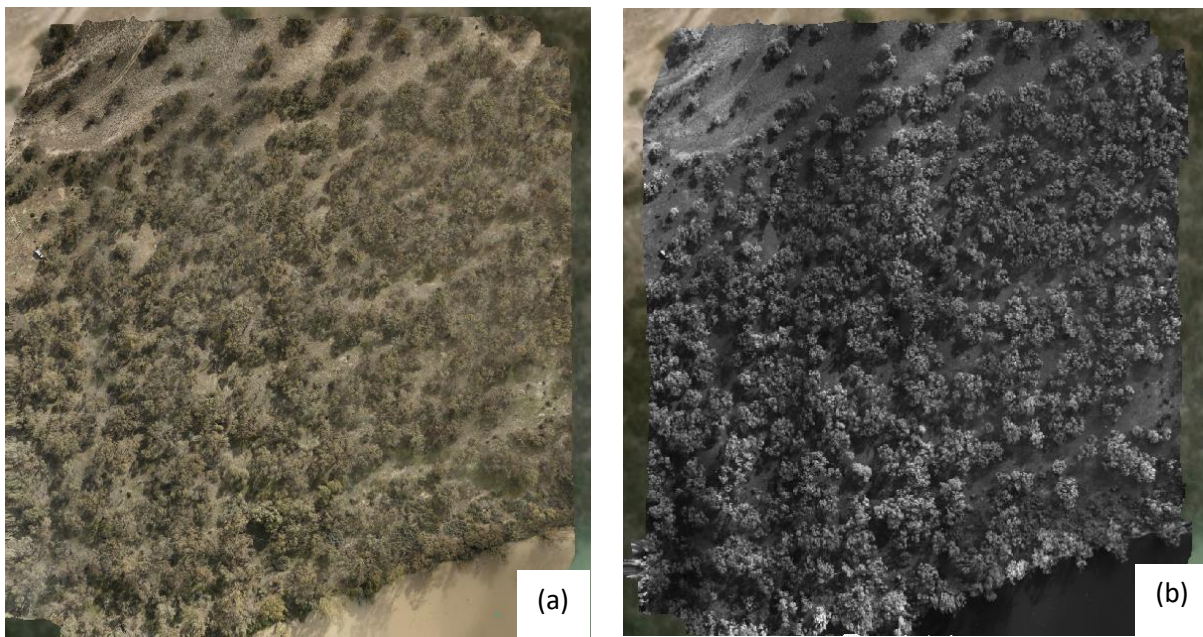


Figure 15: (a) P1 orthomosaic of a Eucalypt Woodlands TERN plot in Calperum, SA (b) Multispectral orthomosaic of the plot with MicaSense Redge-MX Dual NIR band visualised as grey band. The sunlit and dark strips in this orthomosaic are lighting artefacts due to varying cloud cover during the drone flight.

16. In case of any errors in the workflow, the Console tab (Figure 16) or the log file (selected in Agisoft Metashape) will have details on the error and processing step that it appeared on. To fix the error and restart processing using the Metashape GUI, refer to 'Summary of processing workflow using Agisoft Metashape' for equivalent Metashape Toolbar commands. To restart the workflow using a Batch Process refer to 'Appendix 4: Metashape Batch Process'.

Step-by-step processing using the Metashape GUI

This section describes the workflow using Metashape GUI commands. Python script (metashape_upd_cam_pos_only.py) is used to update the rgb and multispec camera positions. The rest of the processing is completed manually using Metashape Toolbar commands.

Add images

Open Agisoft Metashape Pro. Save project with file name format 'YYYYMMDD_PlotName.psx' where YYYYMMDD is the date of data acquisition and PlotName is the name of TERN plot. *Example: 20211012_SASRIV0001.psx.*

1. In the Workspace pane, right-click on 'Chunk 1' and rename to 'rgb'.
2. Choose Workflow → Add Folder and add level0_raw folder under rgb/. (Please note that the folder naming is different in the below screenshot which followed an older naming convention.)
3. In the dialog that opens next, select 'Single cameras' and OK.

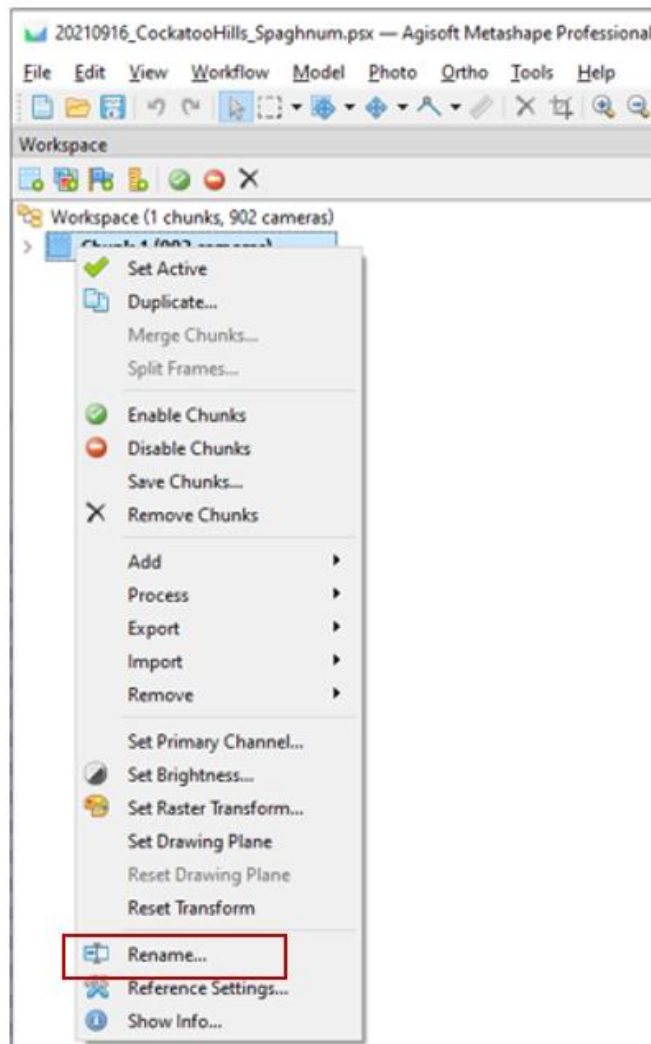


Figure 17: Use the context menu and rename chunk.

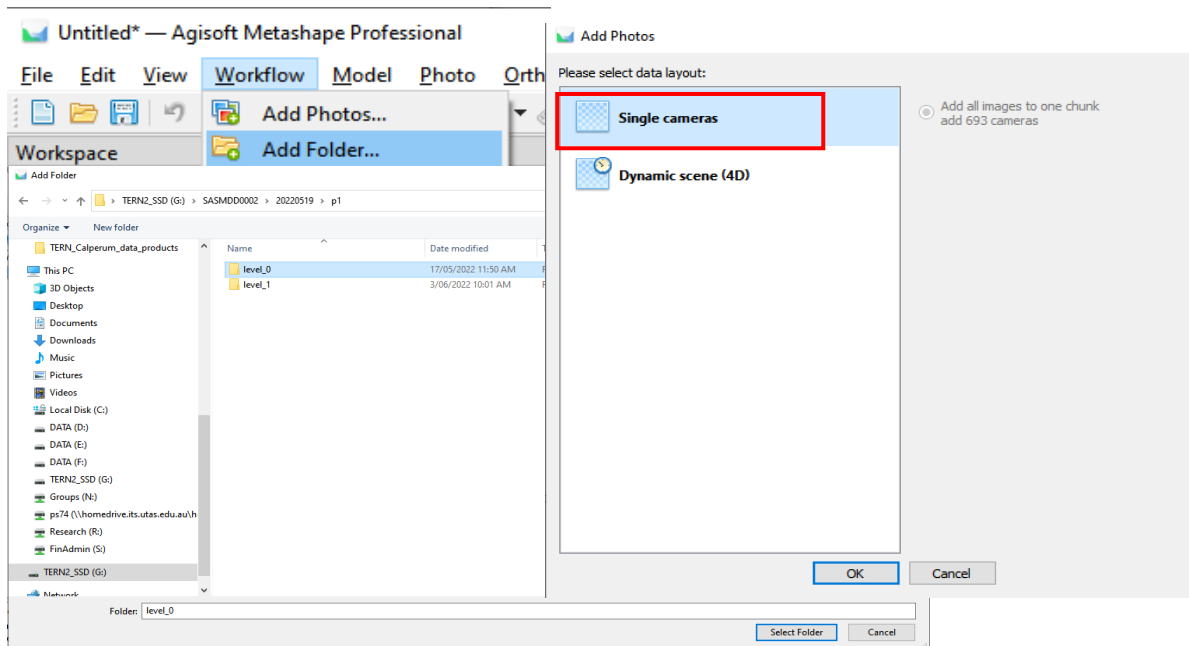


Figure 18: Use Workflow-Add Folder and select 'Single cameras' to add P1 images.

4. Right-click in the Workspace pane to 'Add Chunk'. Right-click on the new Chunk and rename to 'multispec'. Active chunks are shown in bold. If the multispec chunk is not active, double click on it.
5. Add multispectral imagery by choosing Workflow -> Add Folder and add level0_raw/ folder from the multispectral sensor.

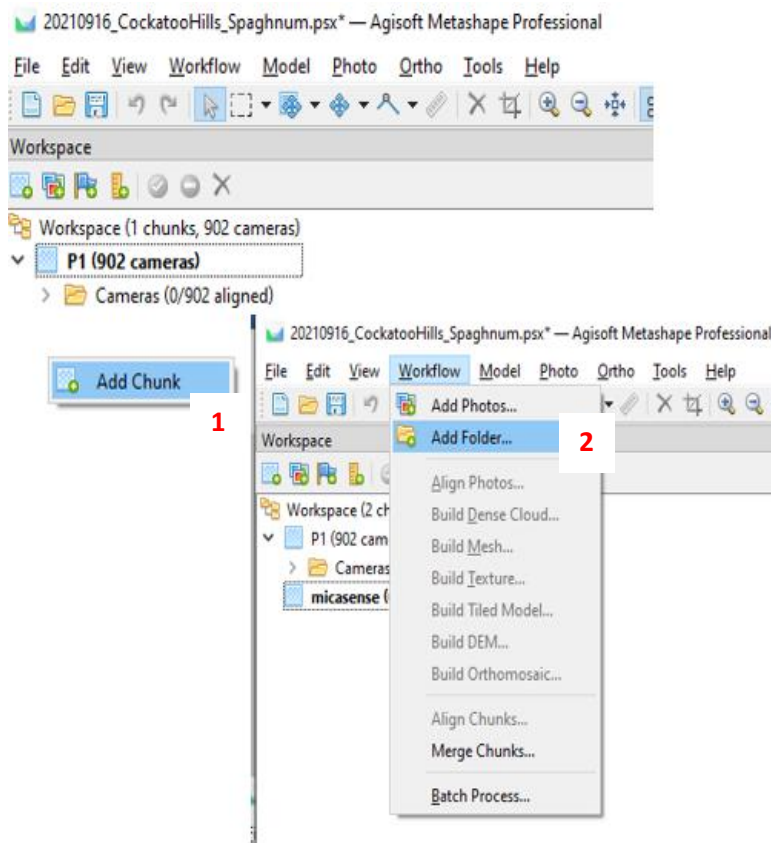


Figure 19: Add folder containing MicaSense images

6. After the photos have been loaded (takes several minutes for large datasets), the following window appears. Select 'Multi-camera system' and click OK.

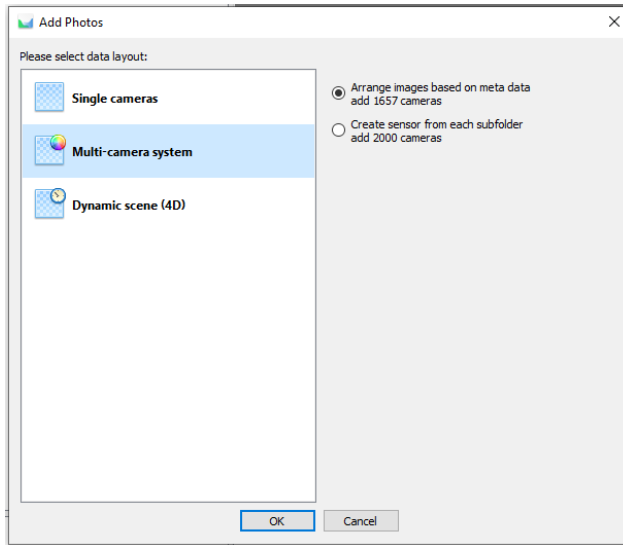


Figure 20: Select 'Multi-camera system' and arrange images based on metadata

7. Any Calibration images automatically detected using the panel QR code will be moved to the 'Calibration images' folder under multispec chunk. Click OK.

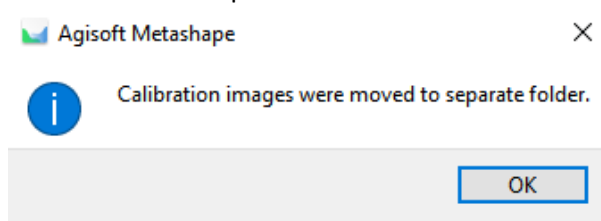


Figure 21: Any calibration images detected using the QR code will be moved to a separate folder.

8. In the main 'Model' window, check that the layout of the flight is as expected. MicaSense data acquisition is started using a target altitude tolerance so there will be images outside of the flight area. These images will be automatically removed in the Python workflow ('Interpolate MicaSense camera positions').

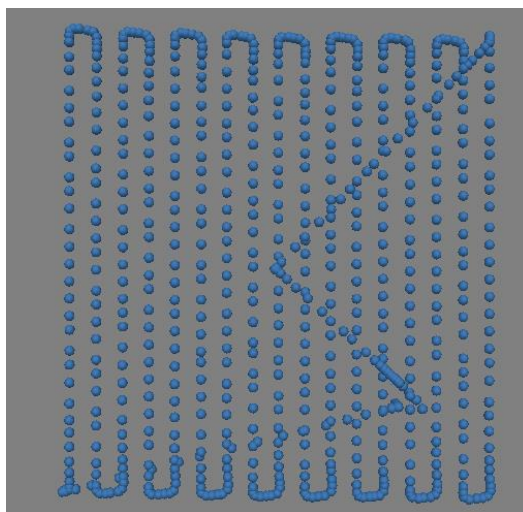


Figure 22: Check layout of flight in the Model window

MicaSense reflectance calibration

Prior to interpolating MicaSense positions and deleting extra images, Calibration Images must be located and moved to the Calibration Images folder so that they do not get deleted.

Note that the following screenshots are from 10-band MicaSense Dual sensor and hence may look different to what is displayed for 5-band RedEdge-MX.

1. Select Tools -> Calibrate Reflectance. Select 'Locate panels'. **This step is necessary even if calibration images have been automatically moved to the Calibration Images group.**

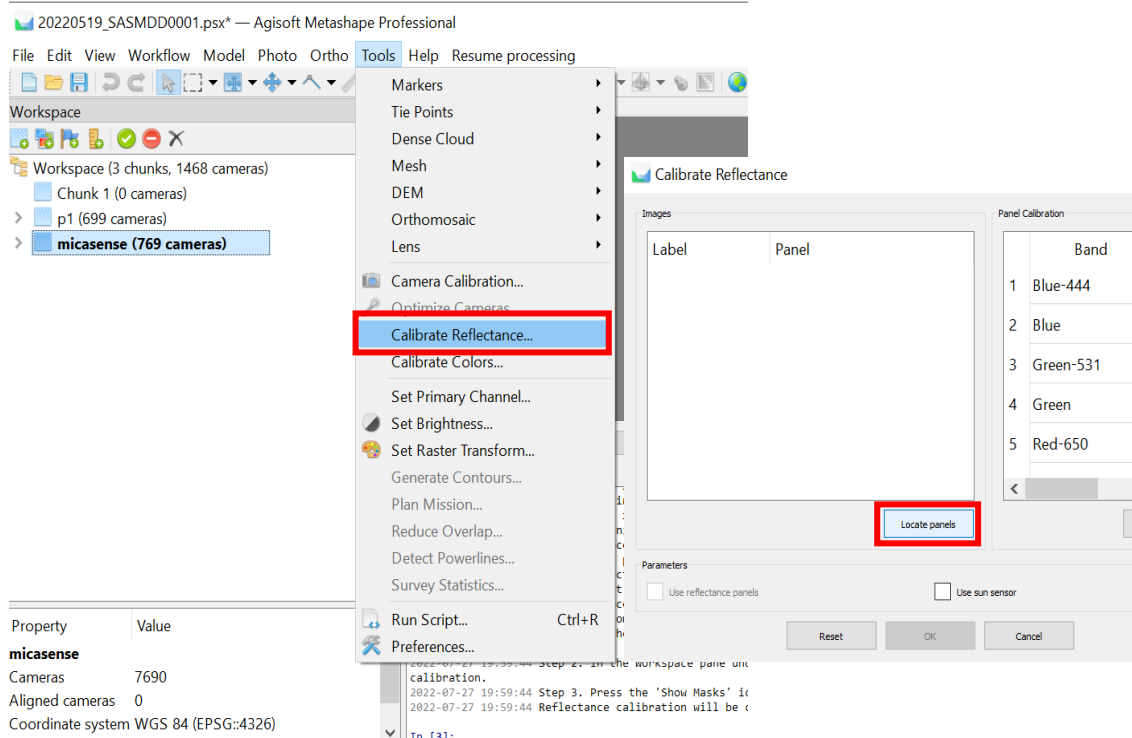


Figure 23: Calibrate reflectance. Select Locate Panels to locate images and set masks for the panels.

2. When the 'Locate panels' step is complete, check that the 'Panel' is the CRP model that was used in the field (look for the right serial number 'RP06...'). The first time this is done, the csv of the calibration panel might have to be loaded (from local drive or contact [MicaSense](#)).
3. Click 'Cancel'. Before reflectance calibration is done, panel masks must be checked, and calibration images chosen from either pre or post flight.

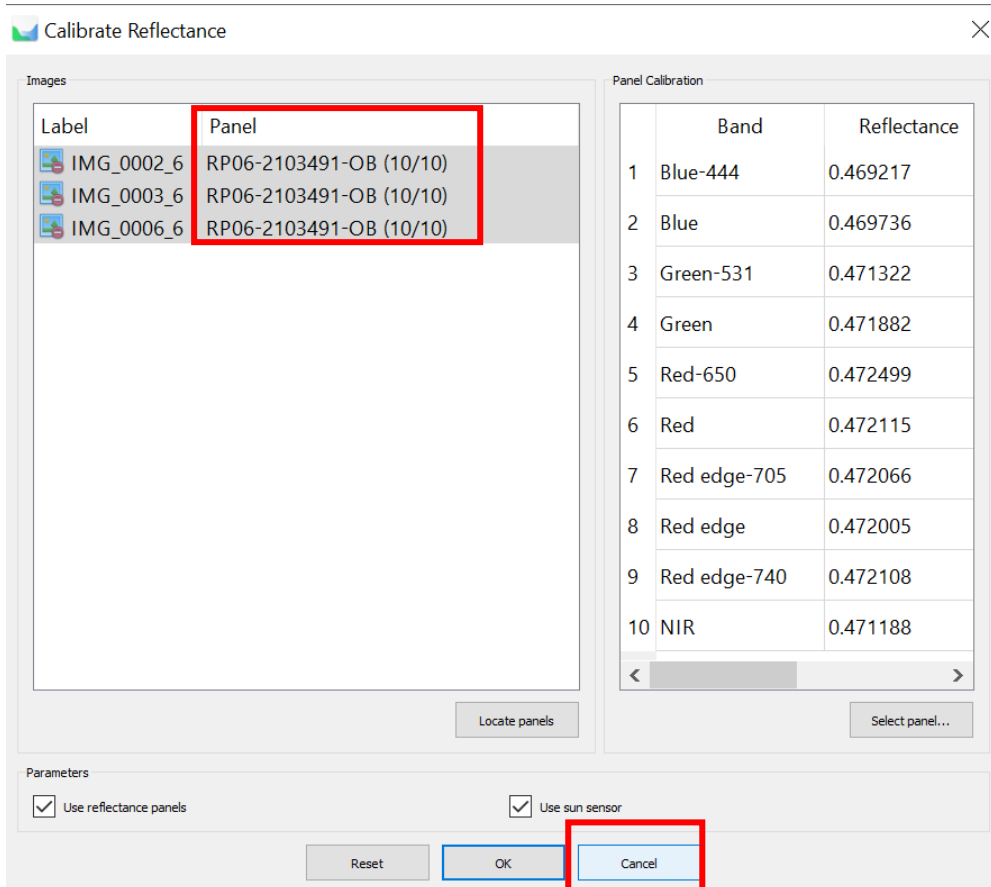


Figure 24: When the panel/images have been located, press Cancel.

4. In the Workspace pane, navigate to the Calibration Images group within multispec chunk. Inspect the photos and identify the ones to use for reflectance calibration.
 - **These images must be sharp and without shadows on the panel.**
 - Check that the entire panel is covered in the image. (If it is not, remove the image by using the context menu and 'Remove Camera').
 - Click on '**Show Masks**' in the photo menu and inspect the mask set by default. Only the panel must be unmasked.
 - If the default mask is not set correctly, fix it manually: in the Photo menu, click on 'Rectangle selection'. Right click on calibration image in the main window, 'Reset Mask', select panel area using 'Rectangle selection', 'Add Selection'. This will set the panel area to be masked. Now select 'Invert Mask'. Repeat for all channels of all images to be fixed.
 - Repeat this for other channels (change the channel displayed using Tools -> Set Primary Channel). Repeat for other images in the calibration image folder.

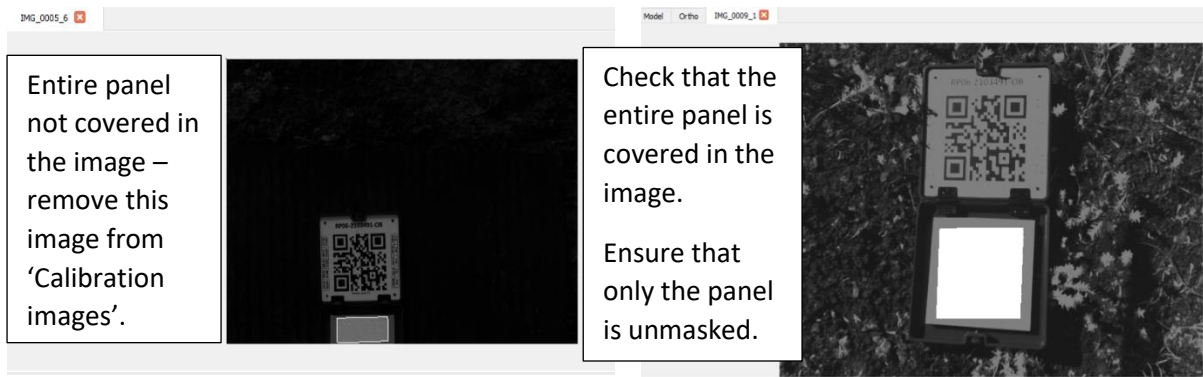


Figure 25: Open calibration images from the folder in micasense chunk to choose images from either pre or post flight. Select images where the entire panel is covered.

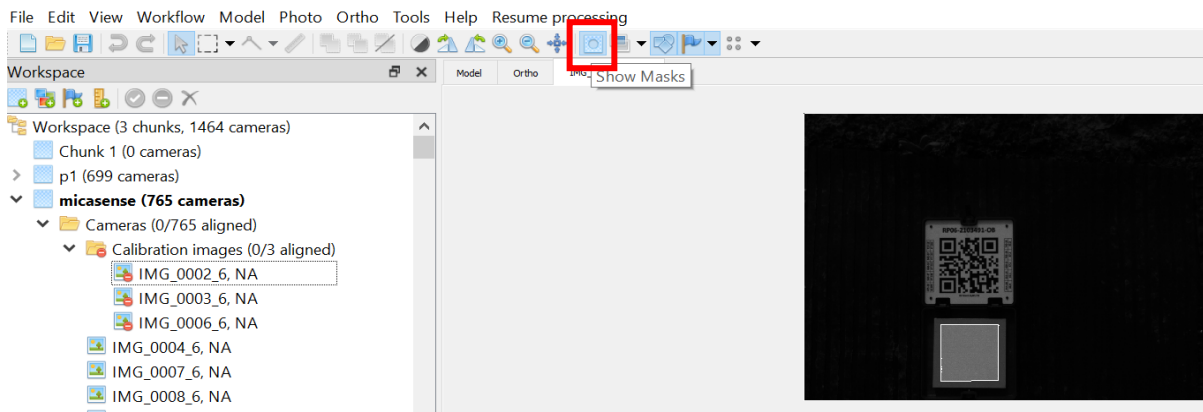


Figure 26: Use the 'Show Masks' icon to inspect the default mask set for the calibration images.

5. Choose images taken at a time (**either from before or after flight**) that best represents the illumination condition during the flight. Finally, select images **that will not be used for calibration** and right-click to 'Remove Cameras'.

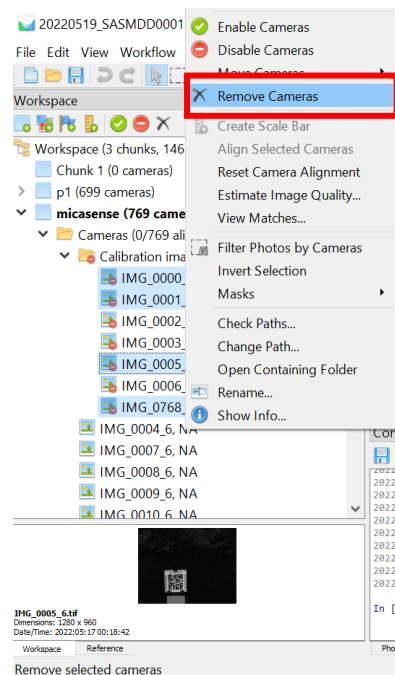


Figure 27: Remove images that are not to be used for calibration.

- Open the Calibrate Reflectance dialog again (Tools->Calibrate Reflectance). Ensure that 'Use reflectance panels' and 'Use sun sensor' are checked. Click OK.

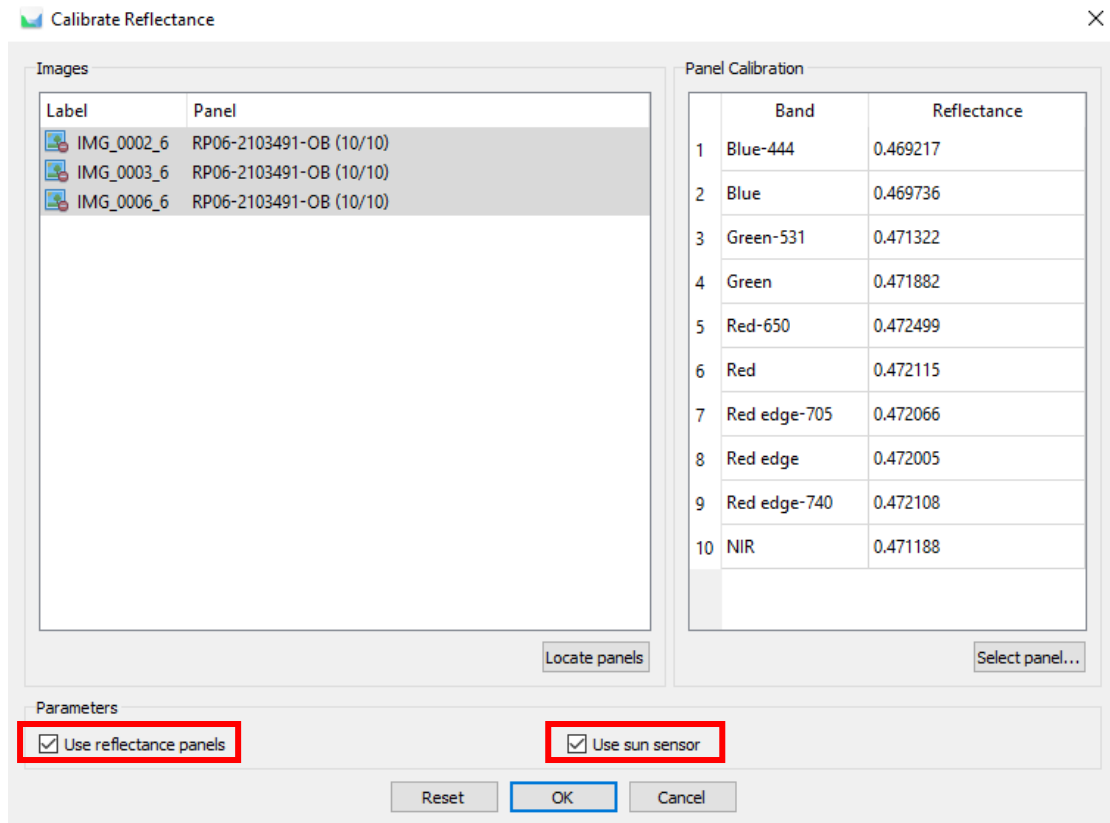


Figure 28: Complete reflectance calibration. Select the correct panel. Check 'Use reflectance panels' and 'Use sun sensor' parameters.

Interpolate MicaSense camera positions

MicaSense camera locations are based on navigation grade GPS. Before processing the imagery, the camera positions must be interpolated using the P1 positions georeferenced using the on-board GNSS RTK. If post-processing of the D-RTK2 base station is required, the script can blockshift P1 camera positions based on the D-RTK 2 coordinates from the AUSPOS report.

The following steps will be done using python script `metashape_only_upd_cam_pos.py`. Install packages as per 'Install external packages'. Refer to Table 5 for information on the arguments and default values.

- Update camera positions in 'rgb' chunk based on AUSPOS D-RTK coordinates (if enabled using `blockshift_p1`).
- Convert coordinates to target projected coordinate reference system.
- Interpolate MicaSense positions using P1 camera positions (sub-second available from MRK file).
- Transform MicaSense coordinates to projected coordinate system to interpolate based on P1 coordinates and timestamps.
- Assign altitude of 0 m to MicaSense images captured outside of P1 acquisition time. Use this value to delete these MicaSense images. (Hence the need to first locate Calibration images in the previous section to prevent their deletion).

Table 5: Arguments and default values for script to update P1 and interpolate MicaSense camera positions `metashape_only_upd_cam_pos.py`

Argument Type	Argument	Value	Default
Required	<code>-crs</code>	EPSG code of output projected coordinate reference system	NA
Optional	<code>-multispec</code>	Path to multispectral images level0_raw folder	Relative to project location: ../multispec/level0_raw
	<code>-rgb</code>	Path to P1 level0_raw folder containing the MRK files	Relative to project location: ../rgb/level0_raw/
	<code>--blockshift_p1</code>	Use when P1 image coordinates are to be blockshifted using AUSPOS result for D-RTK2 base station coordinates. Note the double dash in this argument. It is a 'store true' argument.	NA
	<code>-drtk</code>	If blockshift enabled, txt file containing field and AUSPOS Cartesian coordinates for DRTK (See Appendix 3: Process D-RTK2 base station data)	Relative to project location: ../../drtk/drtk_auspos_cartesian.txt

Run Script

1. Switch to the 'Console' tab to view progress of the script.
2. Select **Tools -> Run Script** (Ctrl +R). Under '**Script**', navigate to the location of the two Python scripts (metashape_proc.py and upd_micasense_pos.py) and select metashape_proc.py.

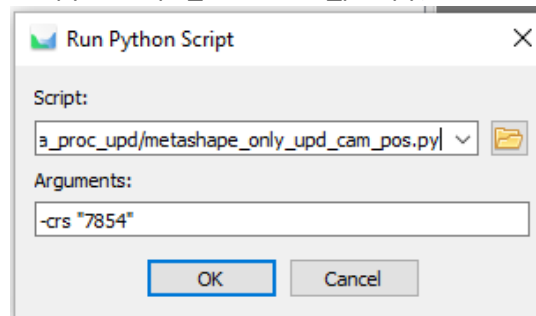


Figure 29: Run script to update camera positions in rgb and multispec chunks.

3. Under '**Arguments**', enter the arguments as necessary **noting that the -crs is a required argument**. See Table 5 for arguments and default values. All argument values must be in double quotes `""`. Click OK.

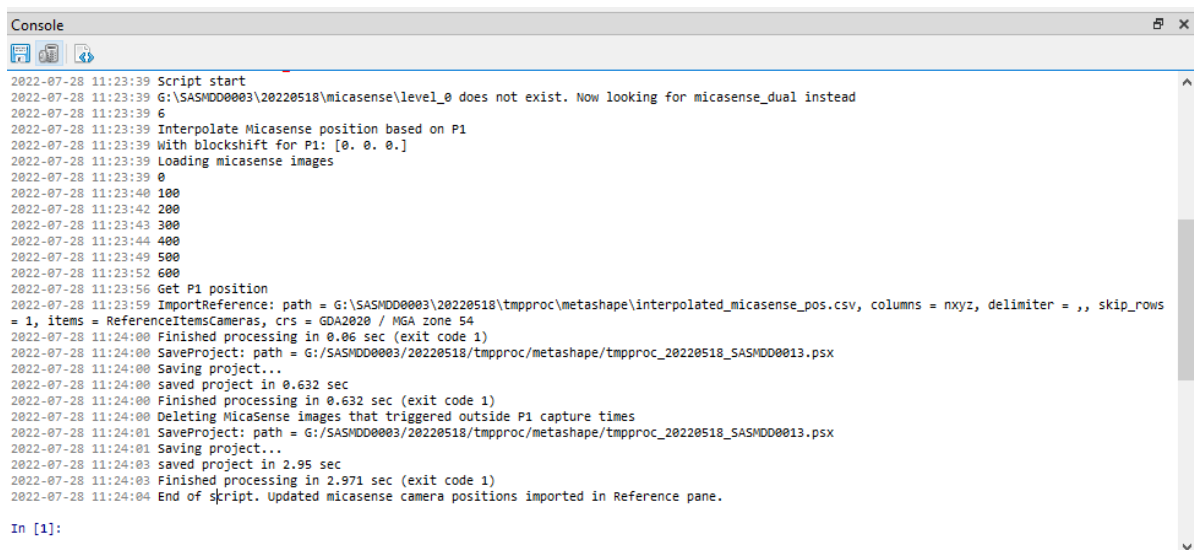


Figure 30: Monitor script progress through the Console tab.

4. Monitor the Console tab for progress of the script.
5. When the script is complete, in the Workspace pane, note that the multispec chunk now has fewer cameras as the extra images have been deleted.
6. In the Reference pane, note that the CRS has been updated to the selected projected CRS. The Altitude (m) column has updated height values based on the P1 RTK locations.

The following sections go over the rest of the workflow on the Metashape GUI.

Zenmuse P1 (RGB)

In the Workspace pane, double click on the 'rgb, chunk to make it active (chunk label must be in bold).

Camera Calibration: GPS/INS Offset

Select Tools-> Camera Calibration to enter lever-arm offsets. The GNSS RTK georeferencing provides the coordinates to the single gimbal position. The offsets from this position to Gimbal 1 (in dual gimbal mount) must be entered to account for the offset in gimbal position (Figure 32). For more information on this setting refer to the Agisoft Metashape Pro manual (Agisoft 2022a).

- In the GPS/INS Offset tab, check 'Enable Reference'. Enter offsets. Offset (m): X: 0.087, Y and Z: 0.

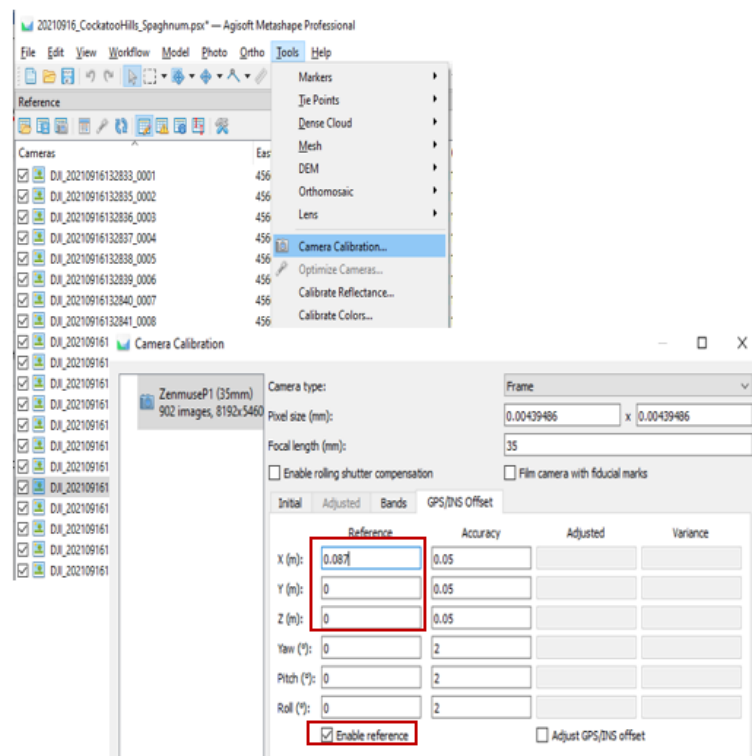


Figure 31: Update GPS offsets for P1 from the single gimbal position

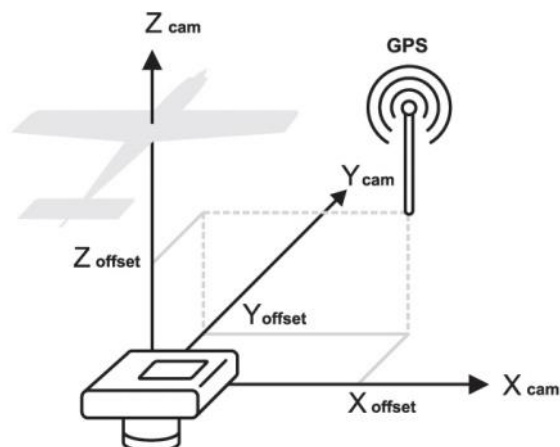


Figure 32: GPS offsets as defined in Agisoft Metashape (Source: Agisoft 2022a)

Inspect camera settings in the Reference pane

- In the Reference pane, check that the Coordinate System has been updated (EPSG was input to the py script in Run Script).

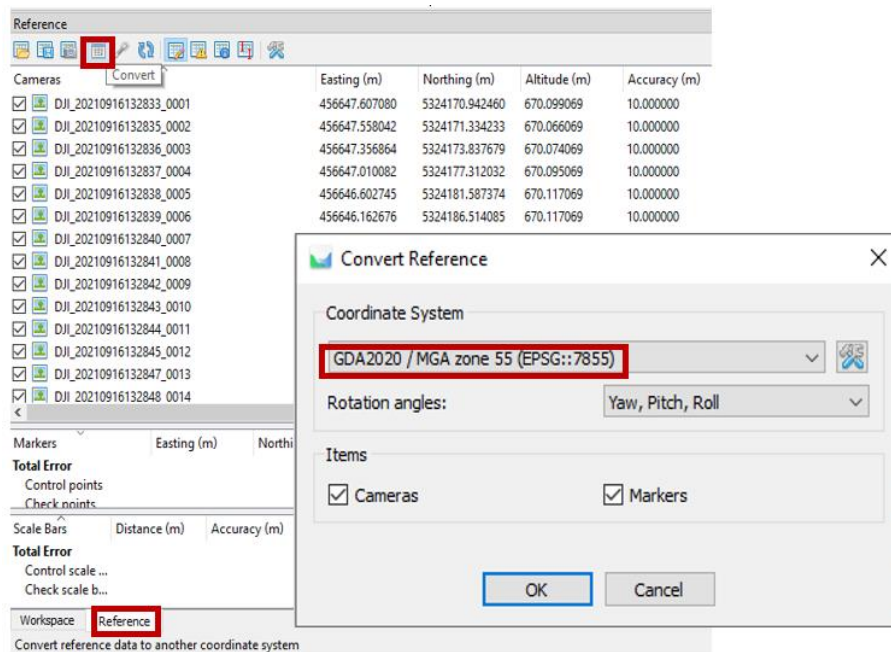


Figure 33: Check that the CRS has been updated as per input to the script.

- Click on 'Settings' icon. Update 'Camera accuracy' to 0.1m which is the expected accuracy for M300 GNSS RTK.

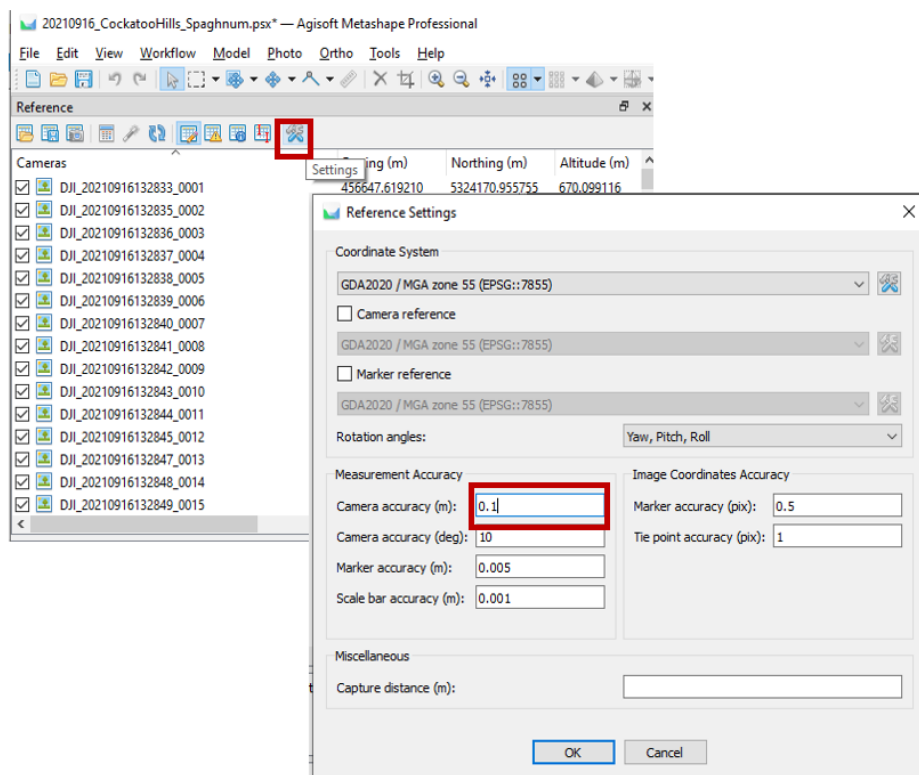


Figure 34: Update camera accuracy to 0.1 m

Disable cameras with low Image quality

In Metashape, Image Quality can be calculated based on the sharpness in the most focused apart of the picture. Metashape recommends that images with low quality value be excluded.

- In the 'Photos' tab, select 'Details' view. Right-click on any image to 'Estimate Image Quality'. In the 'Analyze Photos' dialog, select 'All cameras'.
- When this step is complete, sort photos based on 'Quality' column. Inspect images with Quality less than 0.7. Right-click on these image(s) to 'Disable cameras'.

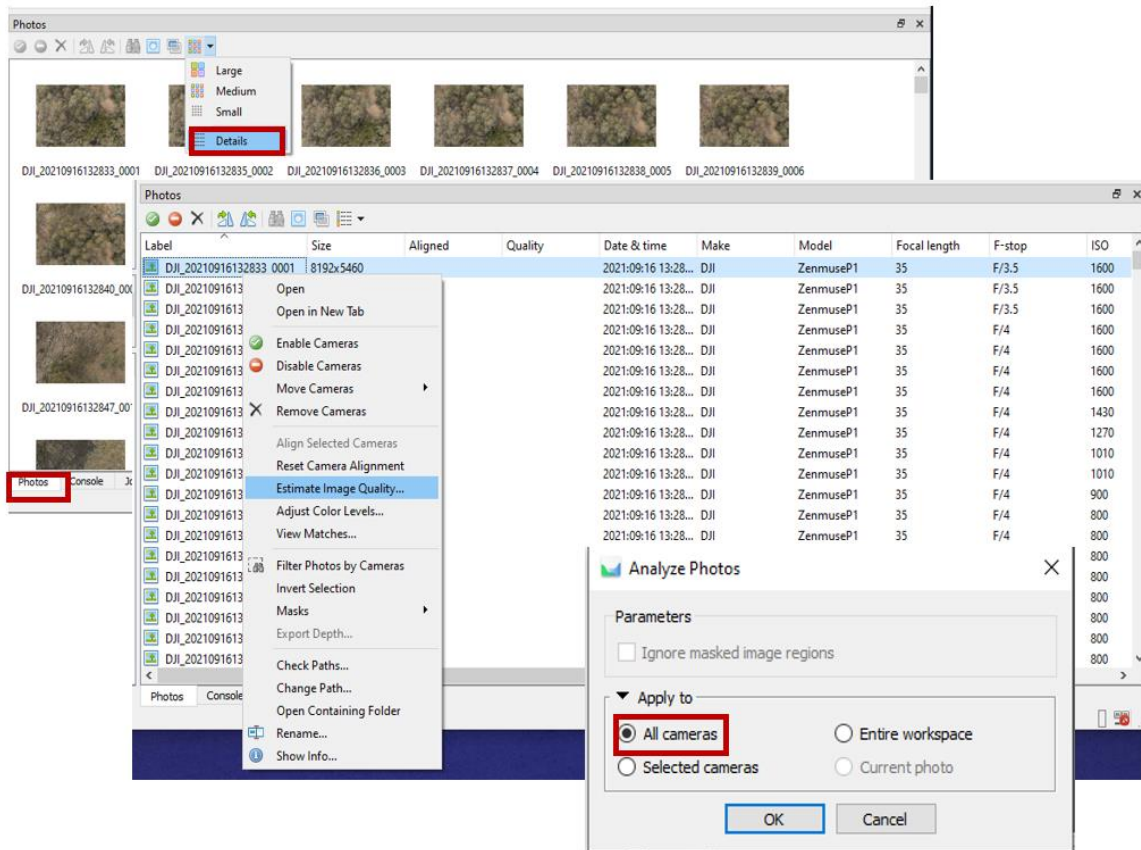


Figure 35: Estimate image quality for all cameras.

- Review the camera layout in the main window. Remove images captured when the drone was turning at the end of flight lines.

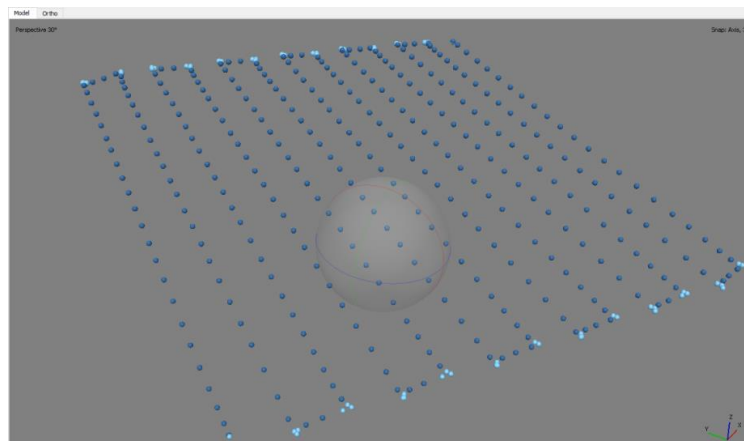


Figure 36: Remove extra images at the end of flight lines

Note on Batch processing: Many of the following steps can be automated using a batch script through Workflow -> Batch Process menu. See 'Appendix 4: Metashape Batch Process' for an example using Batch Process once both the chunks have been setup. Here, the steps are listed separately for the RGB and multispectral chunks.

Align Photos

Image alignment is done to estimate the exterior and interior orientation parameters based on bundle block adjustment (please refer to Agisoft 2022a for more information on this process).

Select Workflow->Align Photos. Use the settings as shown in the image below:

- **Accuracy:** 'High'
- **Reference preselection:** 'Source'. *Select overlapping pairs of images based on the measured camera coordinates. This is recommended as camera locations georeferenced with high accuracy are available.*
- Uncheck 'Generic preselection'. *When enabled, overlapping pairs of images are selected by matching photos at a lower accuracy setting first. However, in drone surveys of TERN plots, where only a few tie points might be detected at the image matching stage, using only Reference preselection without Generic preselection is recommended by Metashape.*
- Use default limits for key point and tie points. *These indicate the upper limit of feature points on every image during the image matching process.*

At the end of this step, a tie point cloud will be generated which can be used to visualise the alignment results.

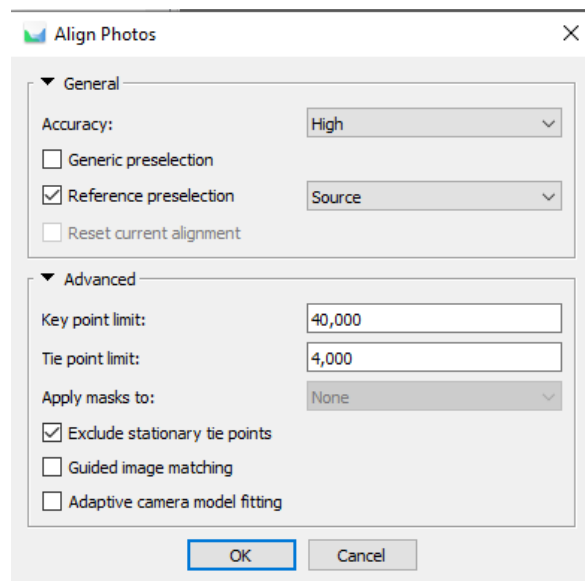


Figure 37: Align Photos with Accuracy: High, Reference preselection set to Source.

Optimise Camera Alignment

This step performs a full bundle adjustment on the aligned images based on available measurements and camera accuracies and can improve the results of the alignment.

- In the Reference pane, ensure that all cameras to be used for optimisation are checked (this is the default setting). Camera accuracy settings were updated earlier in this workflow.
- Click on the 'Optimize Cameras' icon.
- Use the default settings (shown in figure below):
 - General: Fit f, k1, k2, k3, cx, cy, p1, p2
 - Disable Advanced settings

For more information on the values being optimised, refer to the Agisoft Manual (Agisoft 2022a).

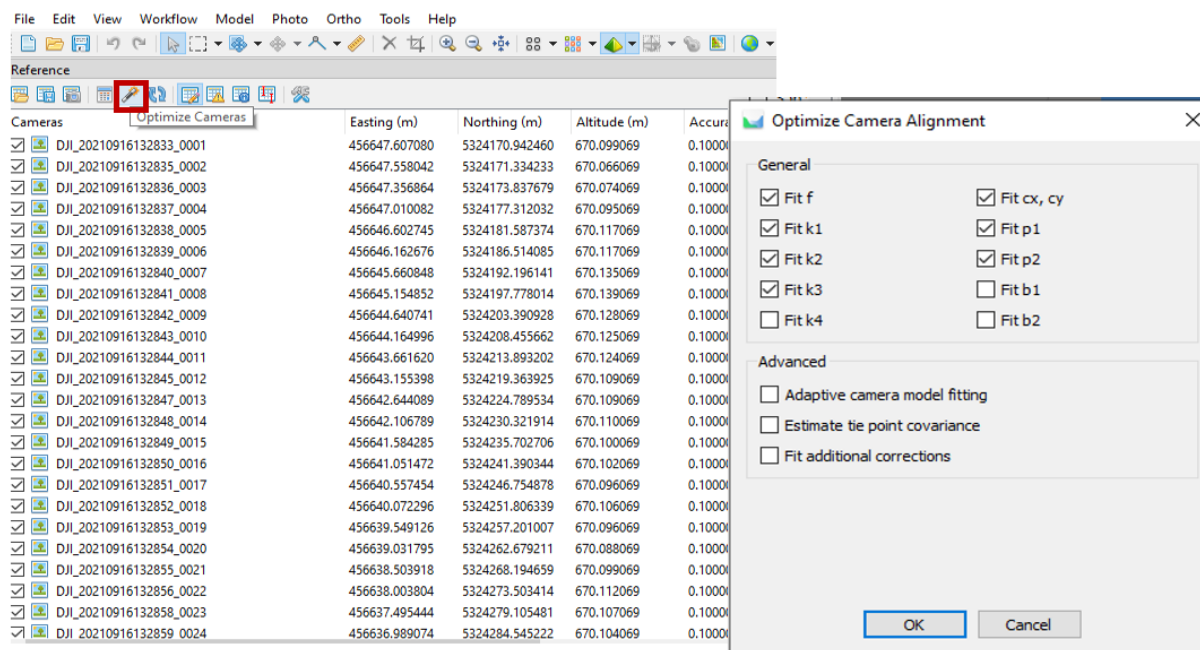


Figure 38: Optimise alignment using default settings.

Build Dense Cloud

A dense cloud can be built using the estimated camera positions. Depth maps calculated for the overlapping image pairs are used to generate a dense point cloud.

Select Workflow -> Build Dense Cloud, and enter settings as follows:

- **Quality:** Medium. *Higher quality settings result in a more detailed geometry but require longer processing times.*
- **Depth filtering:** Mild. *Depth filtering mode sets the level of noise filtering, Mild or Moderate are useful for these datasets. Whereas Aggressive could remove more points than intended and Disabled will result in a very noisy point cloud.*

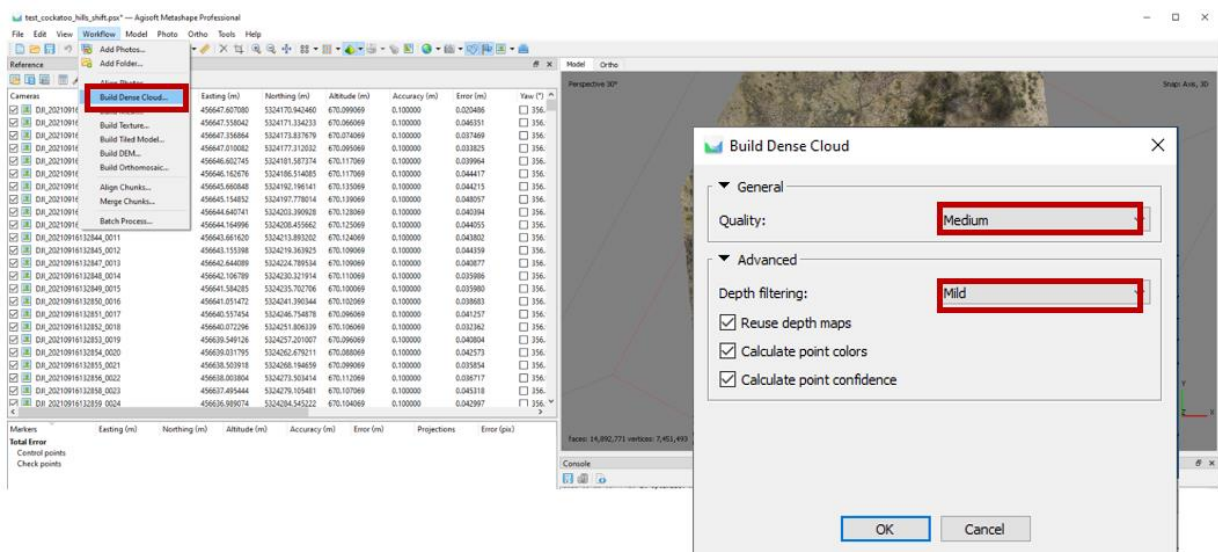


Figure 39: Build dense cloud using mild filtering and medium quality

Orthomosaic generation

Orthomosaic can be built using different orthorectification surfaces, for example:

1. Ground surface generated from lidar point cloud
2. Ground points classified in the photogrammetric point cloud in Metashape, and the resulting surface built from ground points can be used as the orthorectification surface.
3. The dense photogrammetric point cloud can be used to reconstruct a 3D polygonal mesh model which can be used as the surface.
4. The surface model as above smoothed to remove artefacts due to sharp differences in height e.g., canopy edges.

The surface used depends on the intended use of the orthomosaic e.g., is geometric accuracy of trees in orthomosaic important for the analysis? It is also likely to be determined by the complexity of vegetation on the site. For example, classifying ground points in the photogrammetric point cloud tends to have poor results in densely vegetated sites. Further research/testing is required to establish optimal settings for different environments.

Here a polygonal mesh is generated from the dense cloud. The mesh is smoothed to remove artefacts (e.g., on the edges between tree crowns and ground in complex vegetated environments) and used to project the images.

Build Mesh

Select Workflow->Build Mesh.

- **Source data:** Dense cloud
- **Surface type:** Height field. *The surface type is optimised for modeling planar surface rather than an arbitrary object.*
- **Face count:** Medium. *Used to identify the maximum number of polygons in the final mesh. A low value might be appropriate (in which case the decimate mesh step below could be skipped) but needs further testing to compare results (To do list).*
- Use default values for other settings.

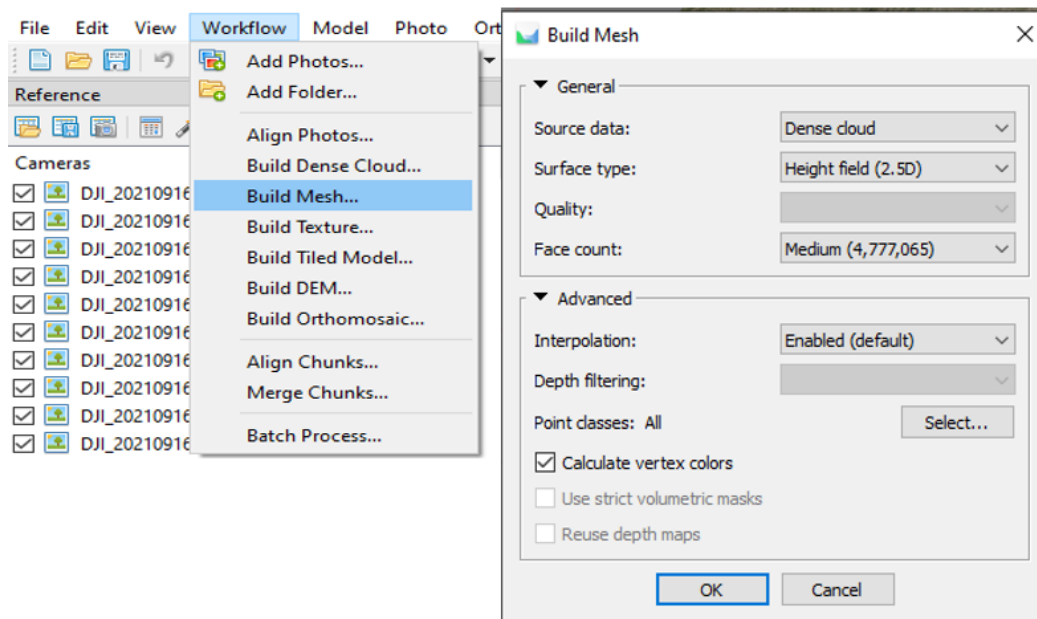


Figure 40: Build mesh from dense cloud. Surface type: Height field, face count: Medium.

The aim is to create a smooth surface to project the images. With the medium quality mesh, this is done by decimating and smoothing the mesh surface as follows.

Decimate Mesh: Select Tools-> Mesh->Decimate mesh. Enter an appropriate value, for example, face count value so that the number of faces in the original mesh is halved.

Smooth Mesh: Select Tools ->Mesh->Smooth mesh. The strength of smoothing depends on the complexity of canopy, hence smoothing must be done in iterative steps. Three values are recommended for low, medium, and high smoothing: 50, 100 and 200 respectively. Further testing on data from densely vegetated sites is required to ensure these settings are appropriate for those environments (see To do list).

To smooth the mesh in iterative steps, start with a small Strength value, inspect the smoothed model, build orthomosaic from each mesh to compare the results. To avoid overwriting the default mesh, first duplicate the mesh using the context menu.

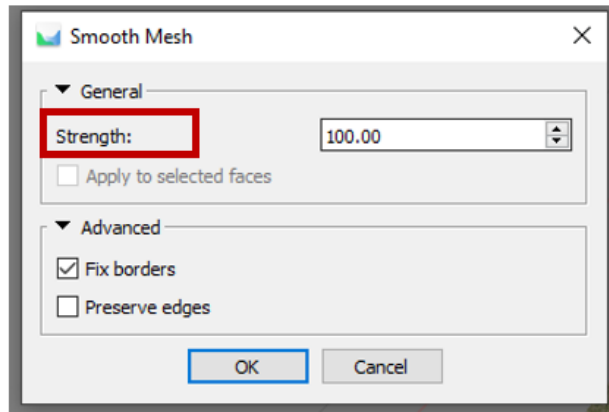


Figure 41: Smooth the mesh in iterative steps.

Export Model

The RGB smoothed model will be used as the surface for MicaSense orthomosaic generation as well to ensure consistency.

- Right click on the smoothed 3D model to export the model.
- Under **Coordinate System** enter the output projected target CRS. Use default values for other settings.
- Save as obj file in the Metashape project directory. Recommended naming format: <project_name>_p1_smooth_<smooth_strength_value>.obj

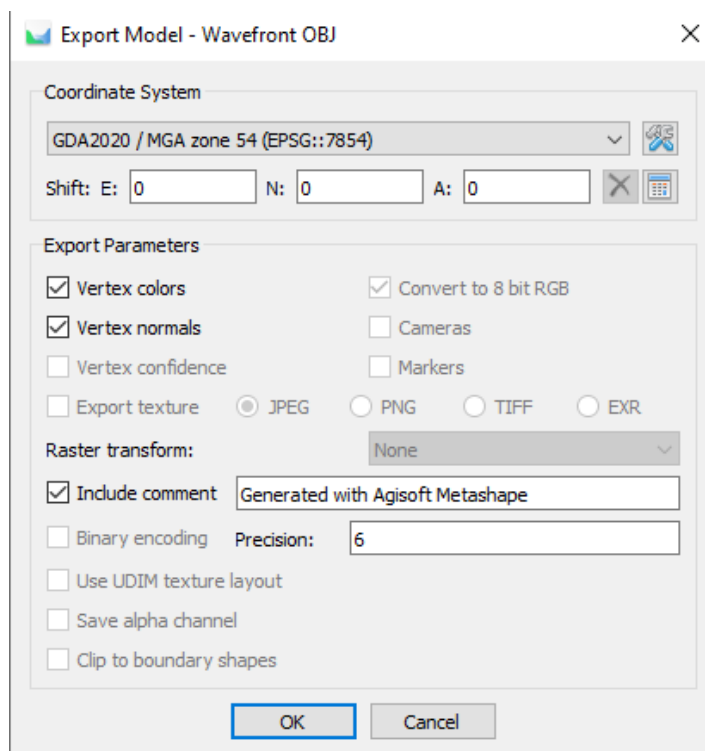


Figure 42: Export smoothed model as .obj file in the target projected CRS.

Build Orthomosaic

In this step the images are stitched together by merging the original images projected on to the smoothed mesh.

- Using the context menu in the Workspace pane, ensure that the smoothed 3D Model is set as default.
- Select Workflow->Build orthomosaic.
- **Surface:** Mesh.
- Enable '**Refine seamlines**': *this will ensure the automatically created seamlines bypass complex vegetation and avoid visual artefacts in the orthomosaic.*
- Use the default pixel size (m).

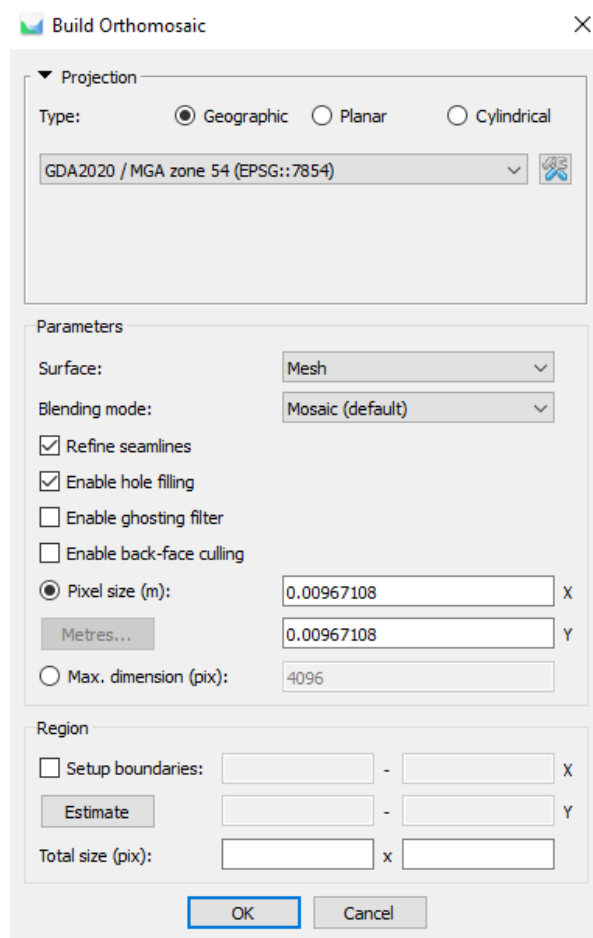


Figure 43: Build orthomosaic using the smoothed mesh

Export Orthomosaic

After the Orthomosaic is generated, in the Workspace pane, right-click on the orthomosaic and select Export Orthomosaic -> Export JPEG/TIFF/PNG.

- Update the Pixel size (round the default resolution to 2 places).
- Select options: 'Write tiled TIFF', 'Write BigTIFF file', 'Generate TIFF overviews'
- Accept other default settings
- Save the tiff in rgb/level1_proc/ directory. Recommended naming format is <project_name>_p1_ortho_<resolution_in_m>.tif

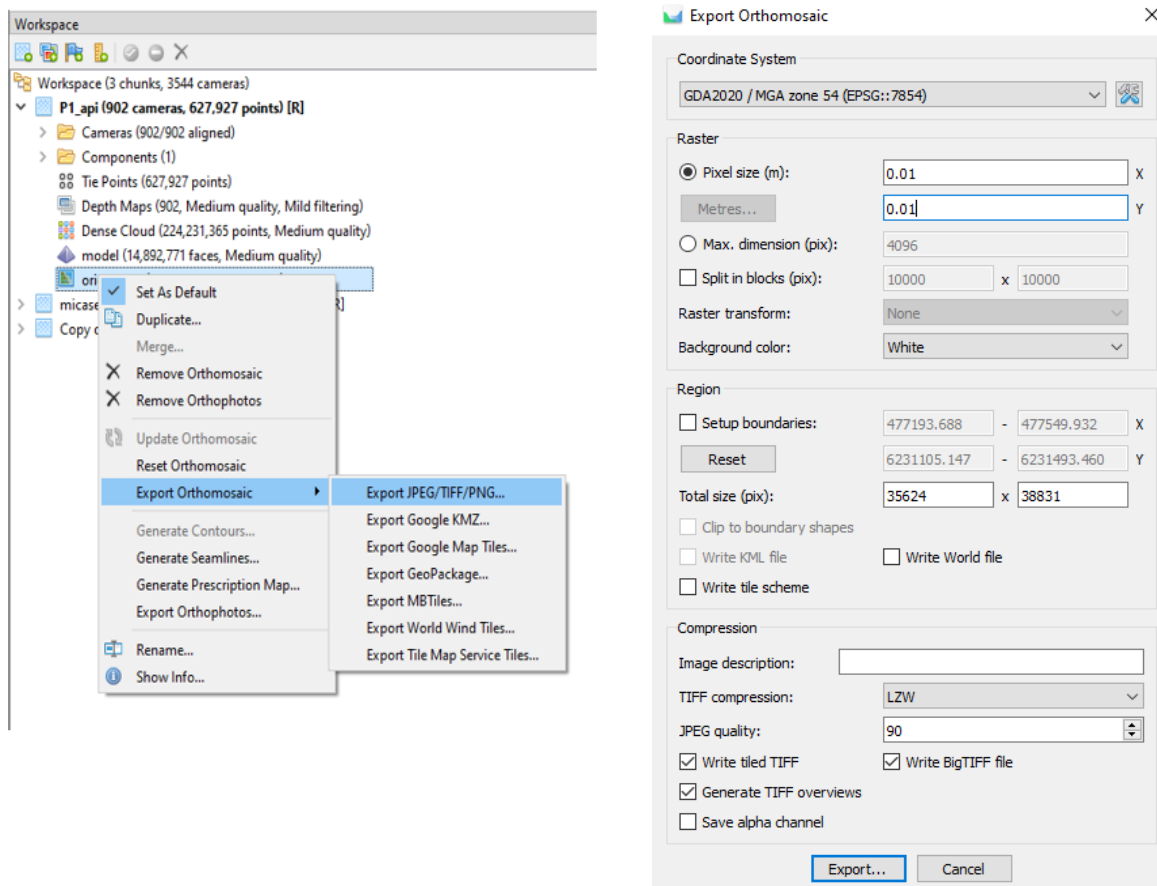


Figure 44: Export Orthomosaic and save as tiff file in rgb/level1_proc/

RedEdge-MX/MicaSense Dual (Multispectral)

In this section, screenshots are included only where settings/parameters vary from the steps used for RGB imagery processing in the previous section.

Camera Calibration: GPS/INS Offset

Select Tools-> Camera Calibration.

- Enter lever-arm offsets (from the single gimbal position). In the GPS/INS Offset tab, check 'Enable Reference'. Enter offsets (m) as follows:
 - MicaSense RedEdge-MX (X, Y, Z): -0.097, -0.03, -0.06
 - MicaSense Dual (X, Y, Z): -0.097, 0.02, -0.08

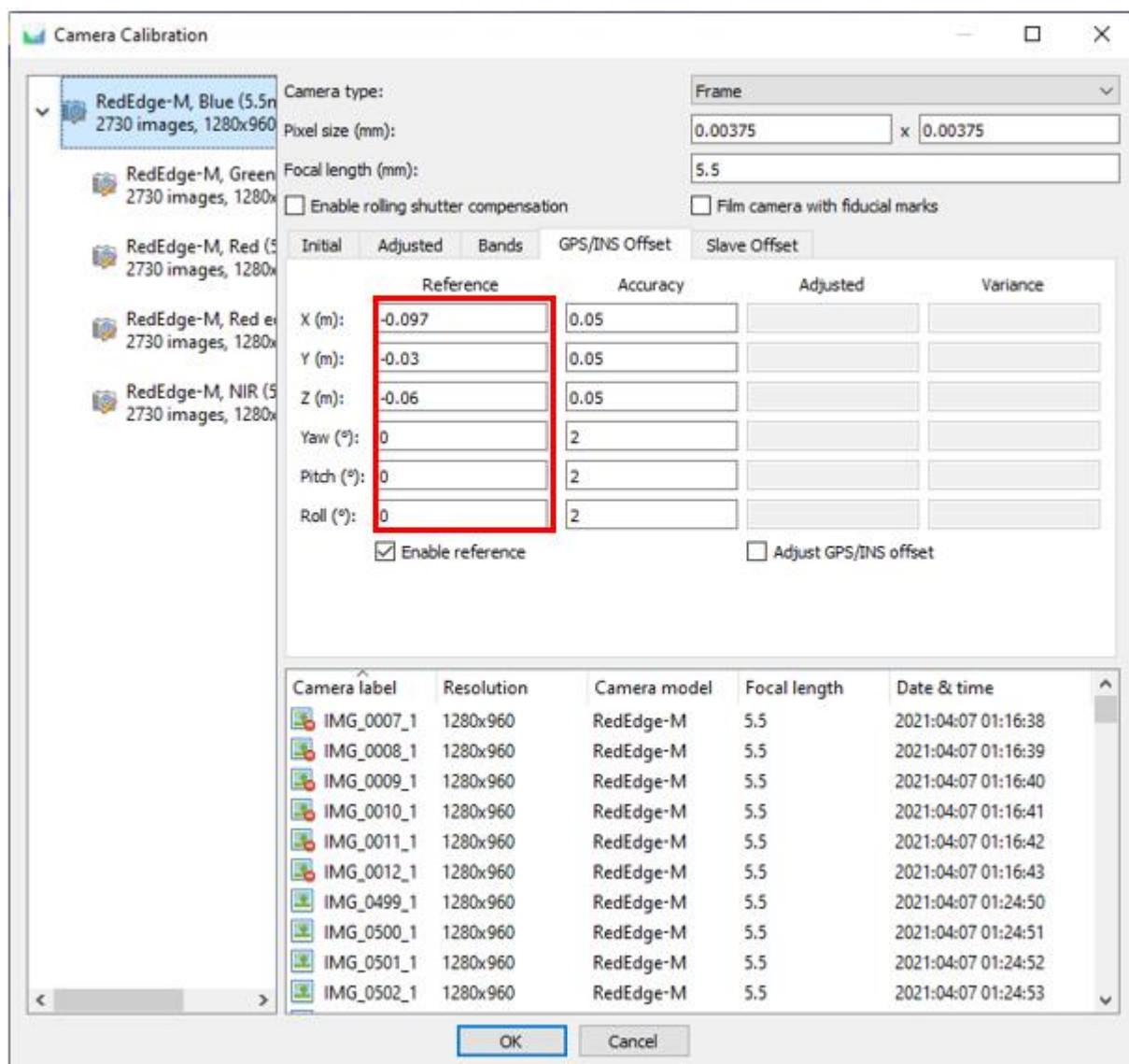


Figure 45: Enter GPS offsets for MicaSense from the single gimbal position

Inspect camera settings in the Reference pane

- In the Reference pane, check that the Coordinate System has been updated (as per the EPSG input to the py script in 'Update Camera positions using python script').
- Click on 'Settings' icon. Update 'Camera accuracy' to 0.1m.

Change Primary Channel and adjust Brightness

For multispectral imagery the main processing steps (Align photos, Build dense cloud, Build Orthomosaic, etc.) are performed on the primary channel. Change the primary channel from the default Blue band to NIR band which is more detailed and sharp.

- Select Tools-> Set Primary Channel. Choose 'NIR' from the dropdown list.
- Adjust image brightness and contrast for better display. Select Tools-> Set Brightness and click Estimate and then OK.

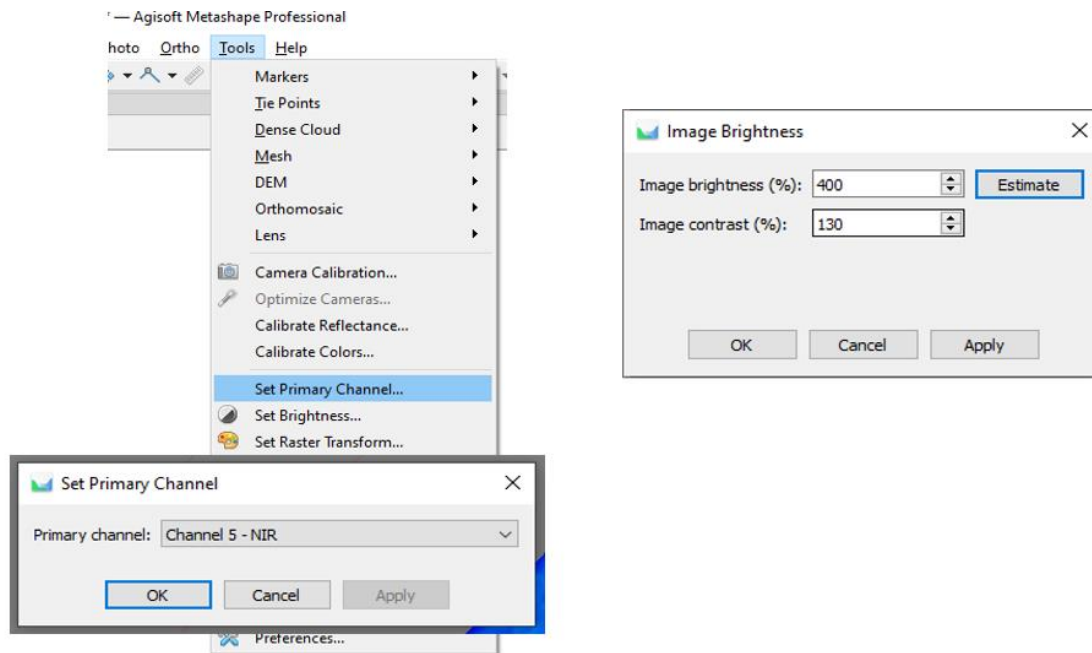


Figure 46: Update Primary channel to NIR and estimate Image brightness.

Disable cameras with low Image quality

- In the 'Photos' tab, select 'Details' view. Right-click on any image to 'Estimate Image Quality'. In the 'Analyze Photos' dialog, select 'All cameras'.
- When this step is complete, sort photos based on 'Quality' column. Inspect images with Quality less than 0.7. Right-click on these image(s) to 'Disable cameras'.
- Review the camera layout in the main window. Remove images that were captured when the drone was turning at the end of flight lines.

Align Photos

Select Workflow->Align Photos.

- Accuracy: 'High'
- Reference preselection: 'Source'.
- Uncheck 'Generic preselection'.
- Use default limits for key point and tie points.

Optimise Camera Alignment

In the Reference pane, ensure that all cameras to be used for optimization (by default, all) are checked. Click on the 'Optimize Cameras' icon. Use default settings (Figure 38).

Build Dense Cloud

Select Workflow -> Build Dense Cloud.

- Quality: *Medium*
- Depth filtering: *Mild*.

Set Raster Transform

To generate an orthomosaic with the reflectance value normalised between 0 and 1, a raster transform must be applied. The pixel values are proportional to % reflectance, with a pixel value of 32768 being equal to 100% reflectance (65535 is equal to 200 % reflectance). So, to generate the reflectance values the pixel values must be divided by 32768.

- Select Tools -> Set Raster Transform.
- To generate an orthomosaic with relative reflectance, in the **Transform** tab, enter the expression $B<num>/32768$ for each band as shown in the figure below. *A pixel value of 32768 is equal to 100 % reflectance and 65535 is equal to 200 % reflectance. To extract reflectance values normalised to 0 – 1 range, divide the source value by 32768 (Agisoft 2022b).*
- Select 'Enable transform'.

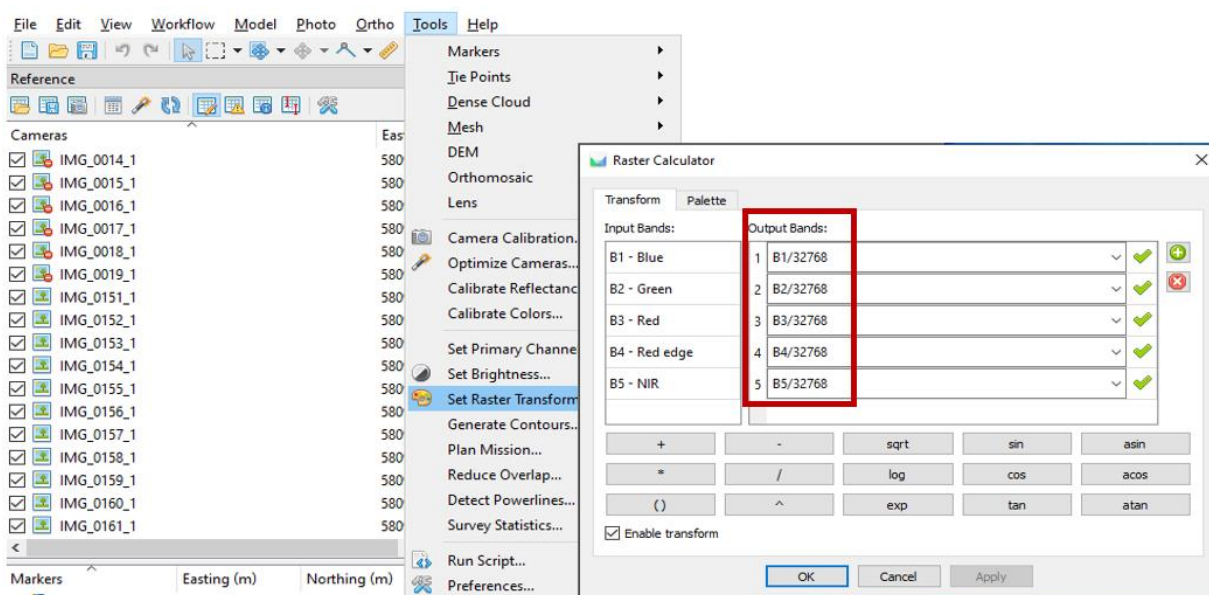


Figure 47: Update Raster Transform to generate an orthomosaic with relative reflectance values. Check 'Enable Transform'.

Import Model

Select File->Import->Import Model and select the .obj file that as exported during RGB imagery processing ([Export Model](#)). Under Coordinate System select the target CRS it was exported in.

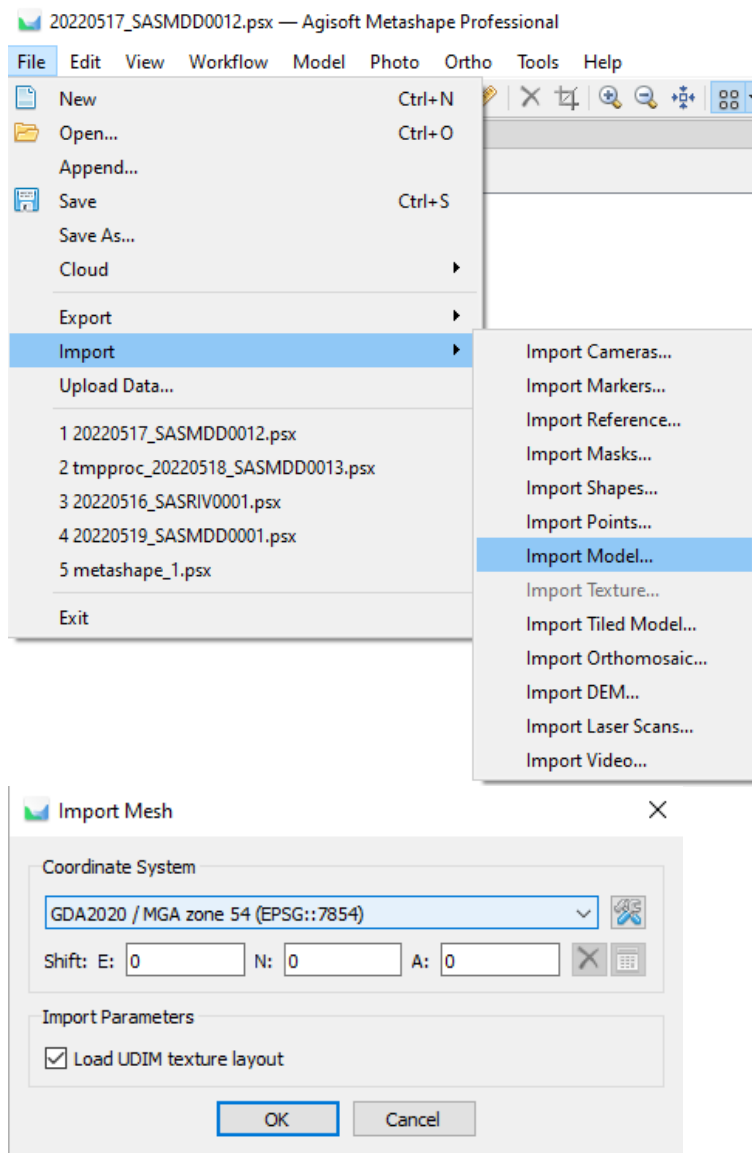


Figure 48: Import smoothed RGB model into multispec chunk

Build Orthomosaic

Select Workflow->Build orthomosaic.

- **Surface:** Mesh
- Enable '**Refine seamlines**'
- Accept other default settings

Export Orthomosaic

Right-click on the orthomosaic and Export JPEG/TIFF/PNG.

- Under **Raster Transform**, select '**Index value**' to export the relative reflectance values
- Update Pixel size with the desired resolution of the orthomosaic
- Select options: 'Write tiled TIFF', 'Write BigTIFF file', 'Generate TIFF overviews'
- Accept other default settings
- Save the file in the level1_proc/ folder under multispec/. Recommended naming is <proj_name>_multispec_ortho_<resolution_in_m>.tif.

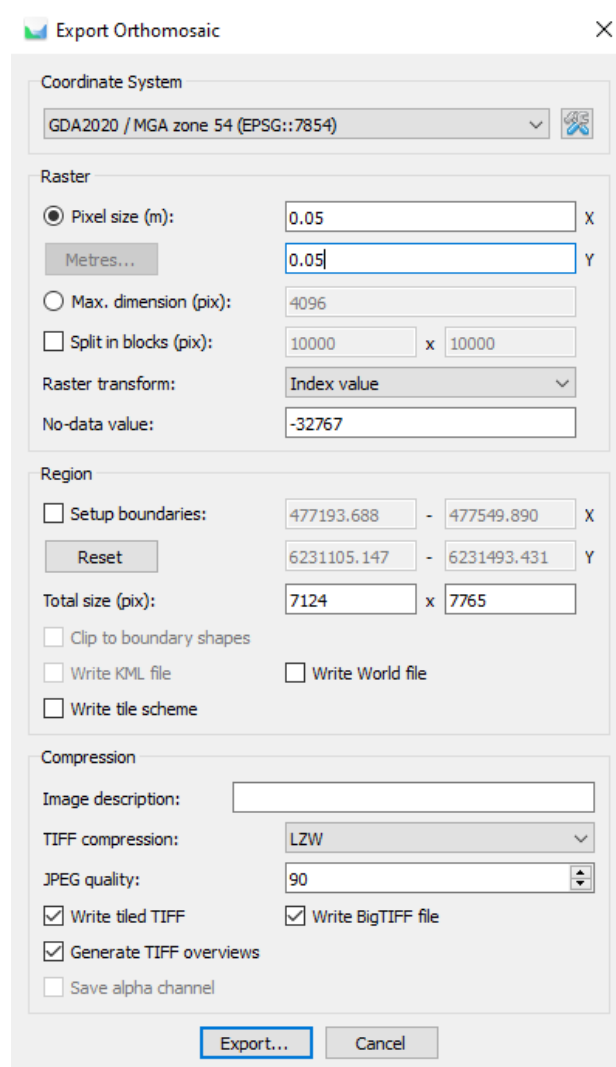


Figure 49: Export orthomosaic. Set Raster transform to 'Index value' to export values set using the formula in previous step.

To do list

1. Surface used to project images: test and compare results using low quality mesh, medium quality mesh with decimating and smoothing, etc. on different datasets.
2. Compare orthomosaic from smoothed mesh and Lidar DEM by digitizing tree canopies and comparing canopy metrics.
3. Test smoothing strength values (low, medium, high) and orthomosaic generation in sites with high vegetation structure/complexity.
4. Processing data on revisits: Test adding revisit data as different camera groups in Metashape and use one set of cameras (from the first visit) for alignment.
5. Test dense cloud classification (settings suggested by Matt Dell) with low-strength smoothing in sites with dense vegetation. Noting that in previous tests, classifying ground points in Metashape did not lead to good results in these sites with ultra-high resolution drone data.
6. Batch script to install external packages.
7. Low priority (revisit if D-RTK2 processing is done frequently for TERN datasets): script to create text file and do some of the D-RTK2 processing in a single step.

References

Agisoft 2022a, Agisoft Metashape Professional Edition User Manual, Agisoft, viewed 28 July 2022, <<https://www.agisoft.com/downloads/user-manuals/>>

Agisoft 2022b, MicaSense RedEdge MX processing workflow (including Reflectance Calibration) in Agisoft Metashape Professional, Agisoft, viewed 19 August 2022, <[https://agisoft.freshdesk.com/support/solutions/articles/31000148780-micasense-rededge-mx-processing-workflow-including-reflectance-calibration-in-agisoft-metashape-pro#3.-Input-reflectance-\(albedo\)-values-of-the-calibration-panel-for-the-bands.](https://agisoft.freshdesk.com/support/solutions/articles/31000148780-micasense-rededge-mx-processing-workflow-including-reflectance-calibration-in-agisoft-metashape-pro#3.-Input-reflectance-(albedo)-values-of-the-calibration-panel-for-the-bands.)>

Appendix 1: Note on folder structure

The automated Python workflow relies on the following folder structure. Raw data must be saved in <plot>/YYYYMMDD/imagery/<sensor>/level0_raw/ (Table 6). Orthomosaic generated using the automated workflow will be saved in rgb/level1_proc/ and multispec/level1_proc/

Table 6: Automated Python workflow relies on the following directory structure for raw data. Processed data and Metashape project will be stored as shown below.

Data	Path
Raw data	<plot>/YYYYMMDD/imagery/<sensor>/level0_raw/ Example: SASMDD0001/20220519/imagery/rgb/level0_raw/
Data products	<plot>/YYYYMMDD/imagery/<sensor>/level1_proc/ Example: SASMDD0001/20220519/imagery/multispec/level1_proc/
Metashape project	plot/YYYYMMDD/imagery/metashape/ Example: SASRIV0001/20220516/imagery/metashape/
DRTK logs	plot/YYYYMMDD/drtk/

Appendix 2: Setting the smoothing strength value

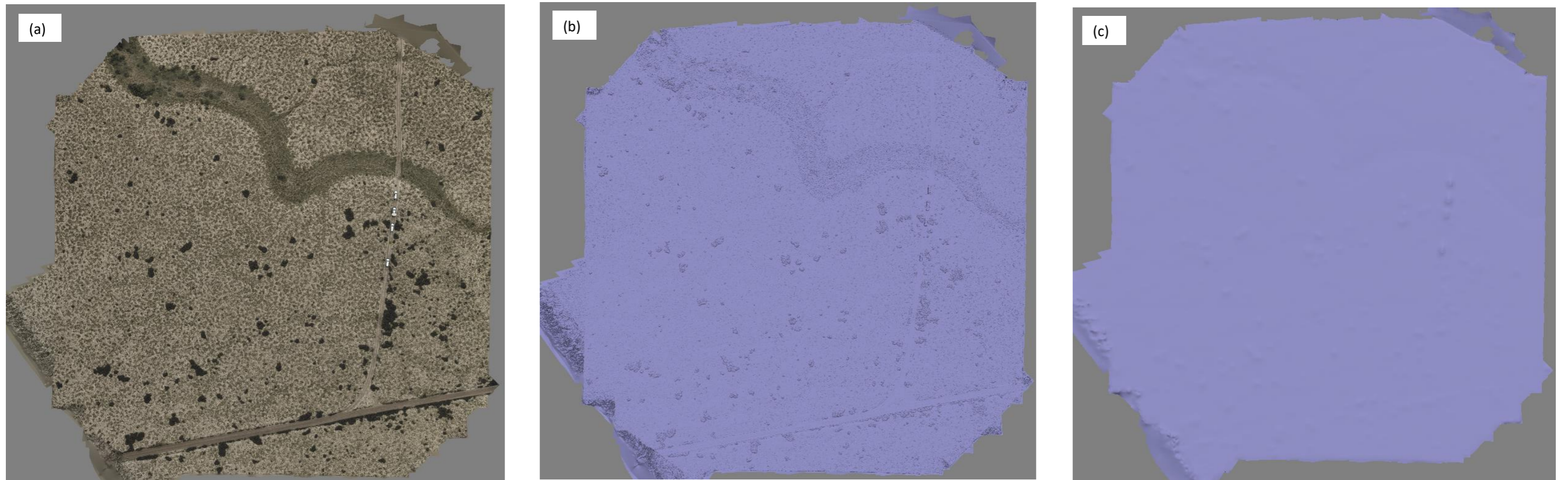


Figure 50: (a) High resolution 3D model of a Samphire shrubland TERN plot. (b) 3D model visualised without shading. (c) Model decimated and smoothed with 'low' strength value 50 to create an orthorectification surface.

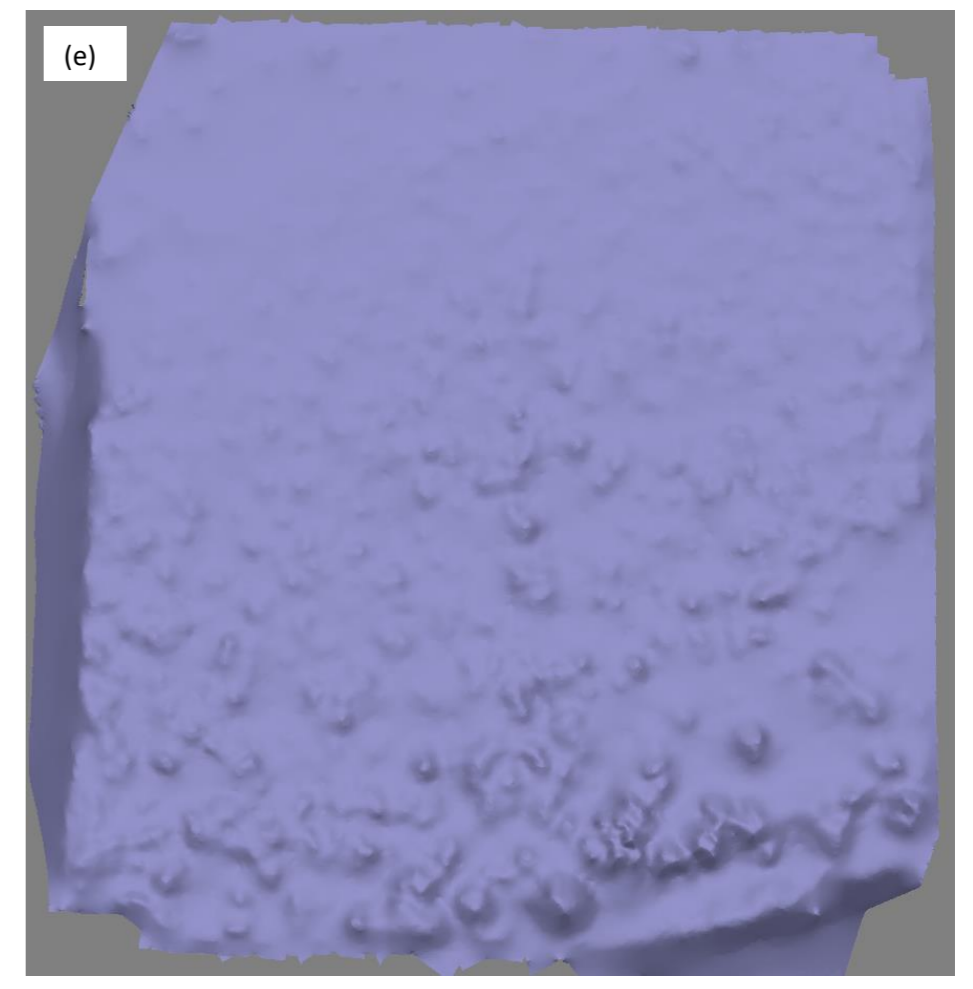
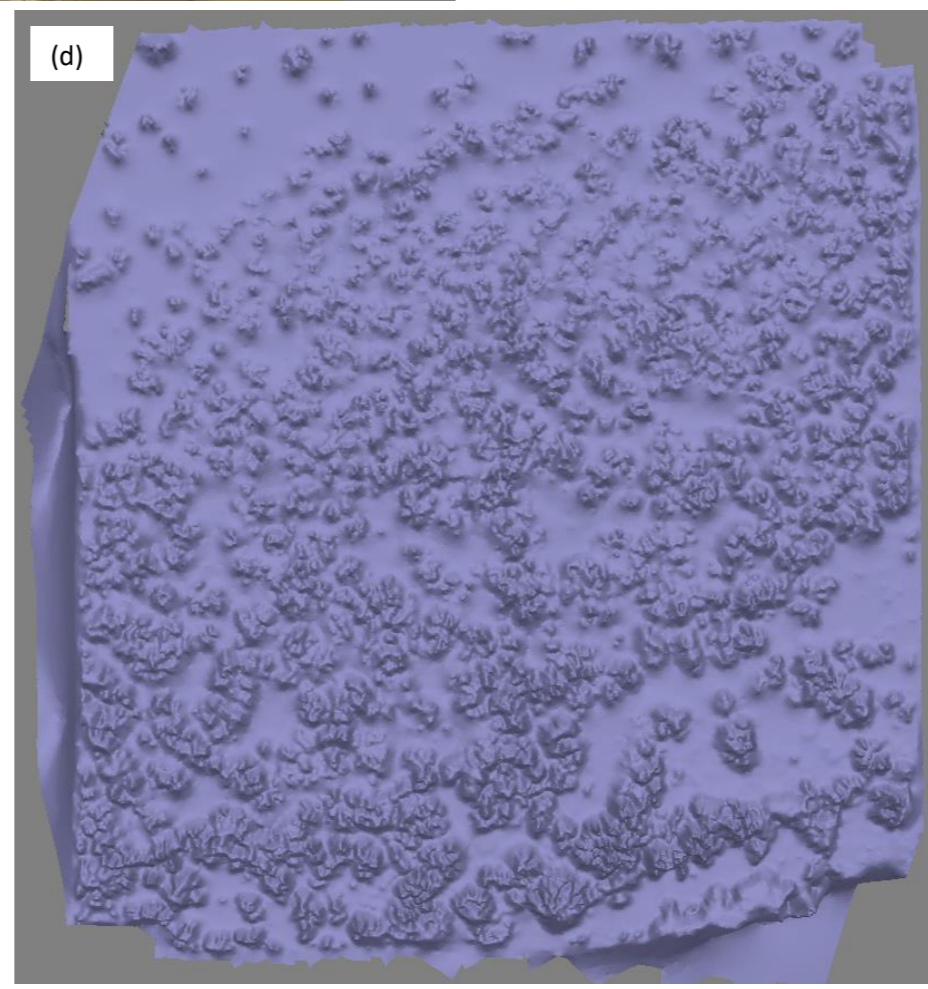
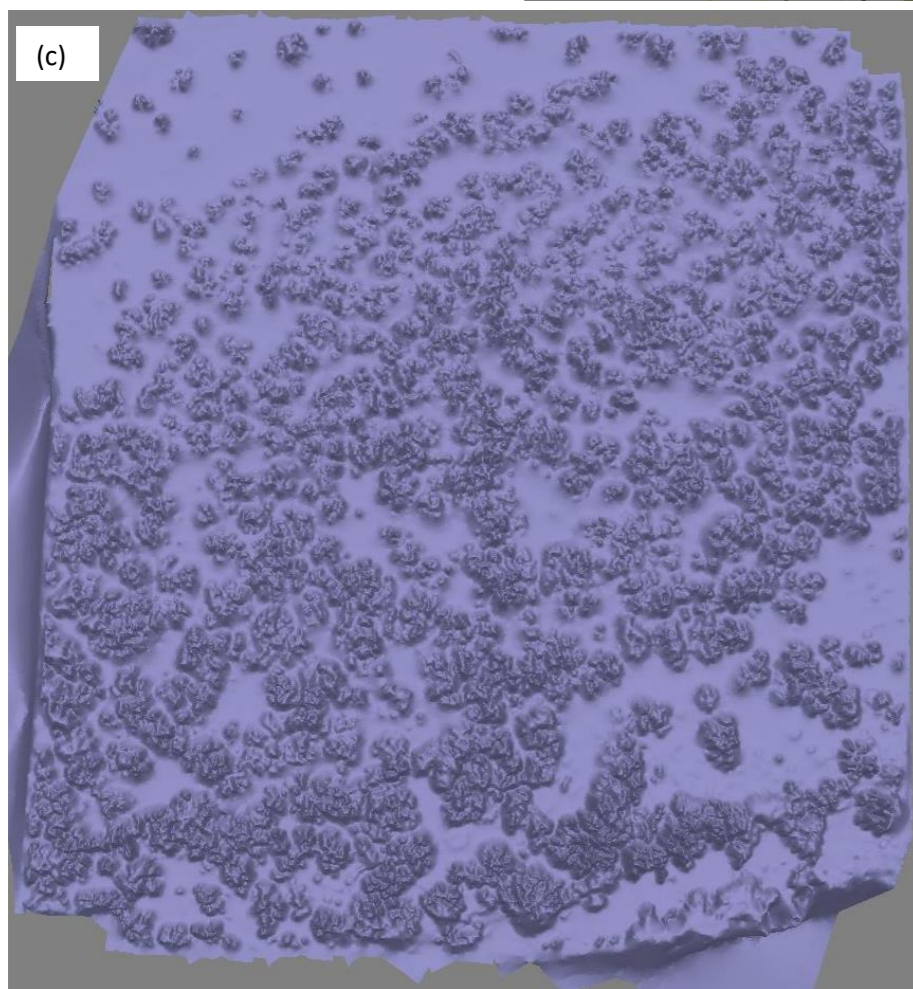
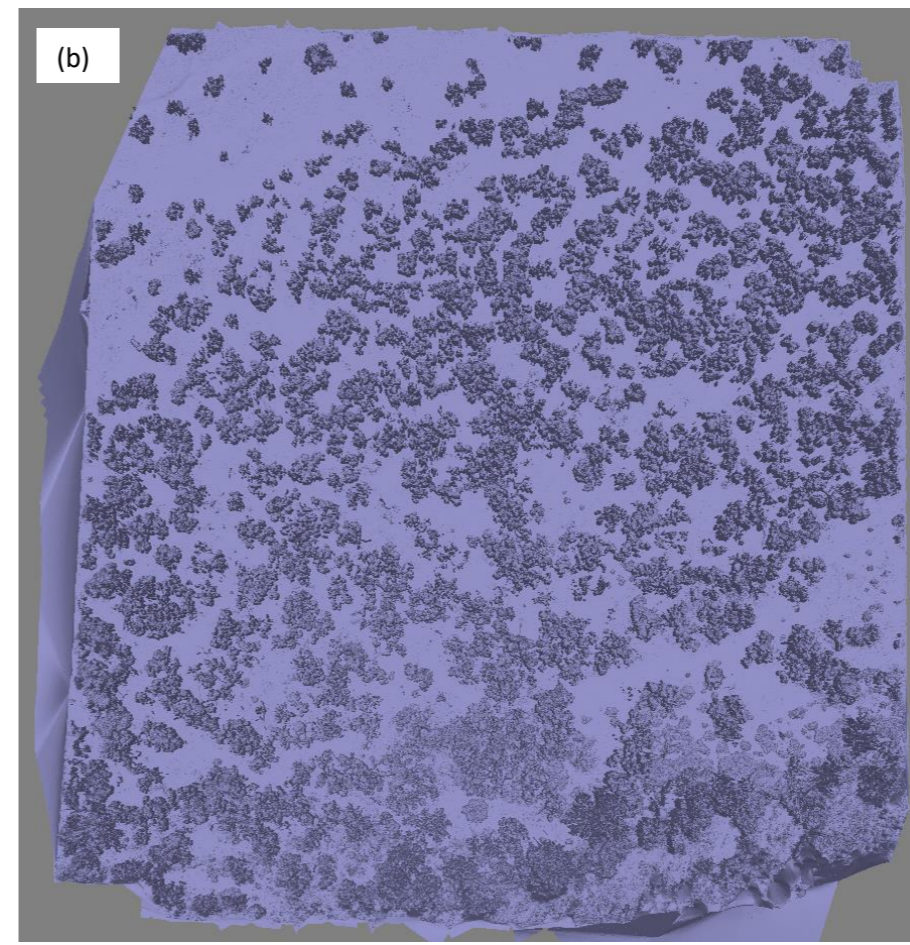
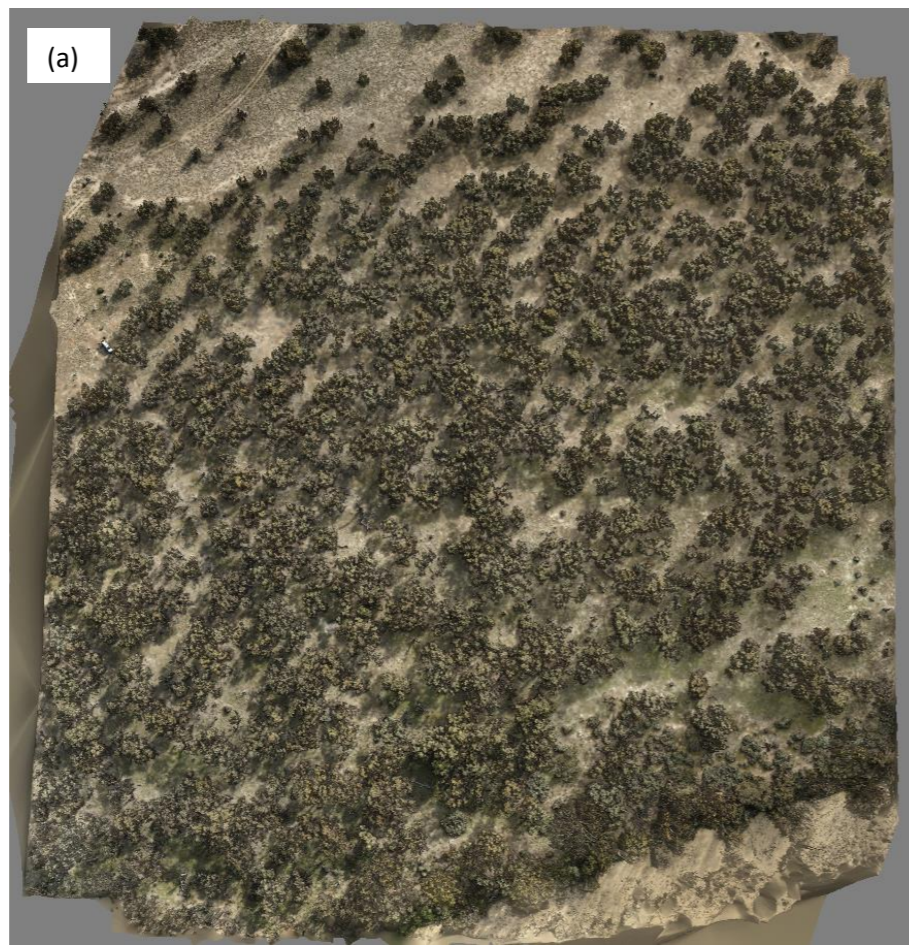


Figure 51: (a) High resolution 3D model of a Eucalypt Woodlands plot in Calperum with average vegetation height ~ 15 m. (b) The 3D model visualised without shading. (c), (d), (e) Default model when decimated and smoothed with low, medium, and high strength values respectively.

Appendix 3: Process D-RTK2 base station data

Raw GNSS data from the D-RTK2 can be post-processed using AUSPOS to refine the position of the base station.

Note that if the D-RTK2 battery was changed, the base location recorded would change although the base station was not moved. In this case the logs (before and after the battery change) must be processed separately.

1. Connect the D-RTK2 via USB to a laptop/computer and copy the RTCM .DAT files from the DRTK2 'rtcmraw' directory on the device and copy D-RTK2 log files to <plot>/<YYYYDDMM>/drtk/
2. RTK files must be converted to RINEX format and consolidated into a single OBS file (an OBS file created for every hour of observations). The merged OBS file must be submitted to AUSPOS for processing. RTK files will be converted and consolidated using RTKLIB (download from <http://www.rtklib.com/>).
3. Open command prompt on Windows. Either use the path to convbin and teqc executables in the following commands or update PATH environment variable to include path to the RTKLIB location using
set PATH = %PATH%;<path to rtklib location>
4. **convbin.exe** converts the DAT file to RINEX format and generates OBS and NAV files. Replace 'OUTPUT_DIR' with the drtk/ folder.

```
convbin.exe -r rtkcm3 -v 2.11 *.DAT -d OUTPUT_DIR -od -os -oi -f 2
```

```
convbin.exe -r rtkcm3 -v 2.11 RTK029_202109160400_13ALH63005007V.DAT -d  
P:\test_cui_rtklib -od -os -oi -f 2
```

Note that **teqc.exe** can be used to consolidate multiple OBS files into one file that can be sent to AUSPOS for processing.

```
teqc.exe ENTER_LIST_OF_OBS_FILES_HERE > DRTKBase.obs
```

```
teqc.exe RTK*.obs > DRTKBase.OBS
```

Or, if only some of the OBS files are to be used, list them separately.

```
teqc.exe RTK027_202109160256_13ALH63005007V.obs  
RTK028_202109160300_13ALH63005007V.obs  
RTK029_202109160400_13ALH63005007V.obs > DRTKBase.OBS
```

5. Decimate OBS file which was sampled at 1 second to 30 seconds as required by AUSPOS.
teqc.exe -O.int 1 -O.dec 30 DRTKBase.OBS > DRTKBaseSubSamp30.OBS
6. Go over the Checklist at <https://www.ga.gov.au/scientific-topics/positioning-navigation/geodesy/auspos>. Under 'AUSPOS Submission', click on 'Submit your data to AUSPOS'.
7. Enter the following information (Figure 52):
 - Click 'Choose File(s)' to select the OBS file(s).
 - Leave the **Antenna Height** as 0, **Antenna Type** as 'DEFAULT (NONE)'.
 - Enter the email address to which the AUSPOS report will be sent.

Load RINEX Files*

File Name	Height (m)	Antenna Type	Status
DRTKBaseSubSamp30.OBS	<input type="text" value="0"/>	<input type="button" value="DEFAULT(NONE) x"/>	Success

Email Address*

No valid antenna type found in DRTKBaseSubSamp30.OBS

You have successfully submitted 1 file(s) for processing. Please quote job number 1634171988195-99999999 should you need to enquire about the status.

- Name: DRTKBaseSubSamp30.OBS
- Height: 0 Antenna Type: DEFAULT(NONE)

Figure 52: Submit OBS file on AUSPOS. Leave Antenna Height as 0, Antenna Type as DEFAULT (NONE).

8. Output report will be received via email; save the report(s) in the drtk/ folder.
9. Create a .txt file in drtk/ named "drtk_auspos_cartesian.txt". Copy and paste the Cartesian coordinates for D-RTK2 from the RINEX OBS file and AUSPOS report (See section Cartesian, GDA2020).
10. In the .txt file, the first line must have the **comma separated** cartesian coordinates from RINEX OBS file and the second line the coordinates from AUSPOS report.

RTK027_202109160256_13ALH63005007V.obs - Notepad

```

File Edit Format View Help
2.10 OBSERVATION DATA M (MIXED) RINEX VERSION / TYPE
RTKCONV 2.4.3 b32 20210921 002057 UTC PGM / RUN BY / DATE
log: R:\SET\Spatial Science\UAV\_data\CockatooHills\202109 COMMENT
format: RTCM 3 COMMENT
unknown UNICORE unknown MARKER NAME
a0001 ADVNULLANTENNA 233 MARKER NUMBER
-3943357.3162 2612482.7744 -4265086.5255 APPROX POSITION XYZ
0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N
1 1
10 C1 L1 D1 S1
2021 9 16 2 56
2021 9 16 3 0
21 9 16 2 56 39.0000000 0
    
```

3.1 Cartesian, GDA2020

Station	X (m)	Y (m)	Z (m)
R000	-3943357.844	2612483.133	-4265086.641
ALIC	-4052052.736	4212835.977	-2545104.584
BUR2	-3989420.916	2699532.929	-4166619.778
HOB2	-3950072.250	2522415.364	-4311637.405
LIAW	-3973071.478	2612407.780	-4238233.888
LILY	-4037356.		
NEWH	-4110936.		
RHPT	-3990736.		
TID1	-4460996.		
TOW2	-5054583.		

drtk_cartesian_coords.txt - Notepad

```

File Edit Format View Help
-3943357.3162, 2612482.7744, -4265086.5255
-3943357.844, 2612483.133, -4265086.641
    
```

Figure 53: Create .txt file with D-RTK2 Base coordinates from the field the OBS file, and the coordinates from the AUSPOS report. Note that the coordinates must be separated by commas in the .txt file.

11. This txt file can be used in the Python workflow (Summary of processing workflow using Agisoft Metashape) to update camera positions. On Agisoft Metashape the difference between the AUSPOS and field positions for the base station will be applied to blockshift the P1 camera station positions.

Appendix 4: Metashape Batch Process

To run Metashape processing in a batch, the commands in Table 2 can be added as a Batch Process using the following example workflow.

1. Select Workflow -> Batch Process. In the dialog select 'Add' to add jobs.

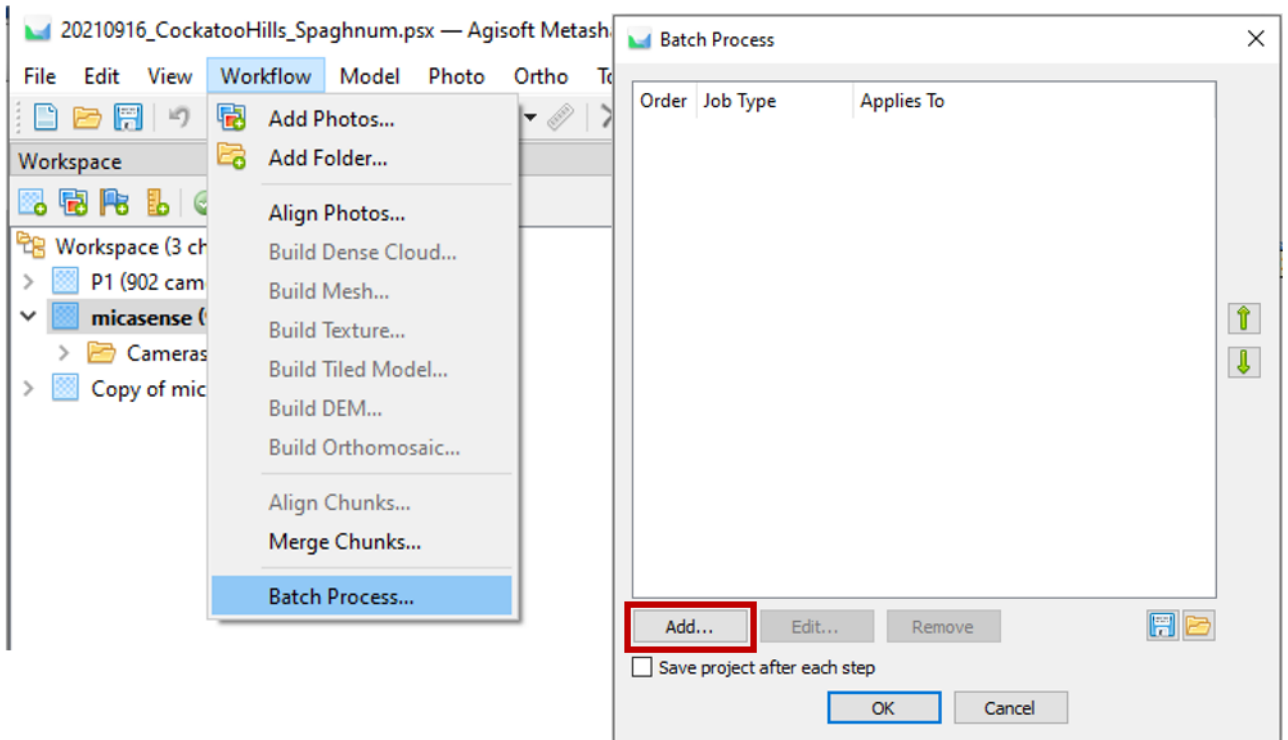


Figure 54: Start a batch process

2. In the Add Job dialog, select the job type from the dropdown list. Select the chunk(s) to run the job on. In the Parameters box, update the settings. Click OK.
3. Repeat the steps to add more jobs. When all jobs have been added, check that the order of the jobs and the chunks they apply to are correct. Use the arrow keys to change the order of the steps. Check the 'Save project after each step' box. Click Ok.
4. Run the batch process in the background (click on Background). Progress can be monitored using the Console tab.

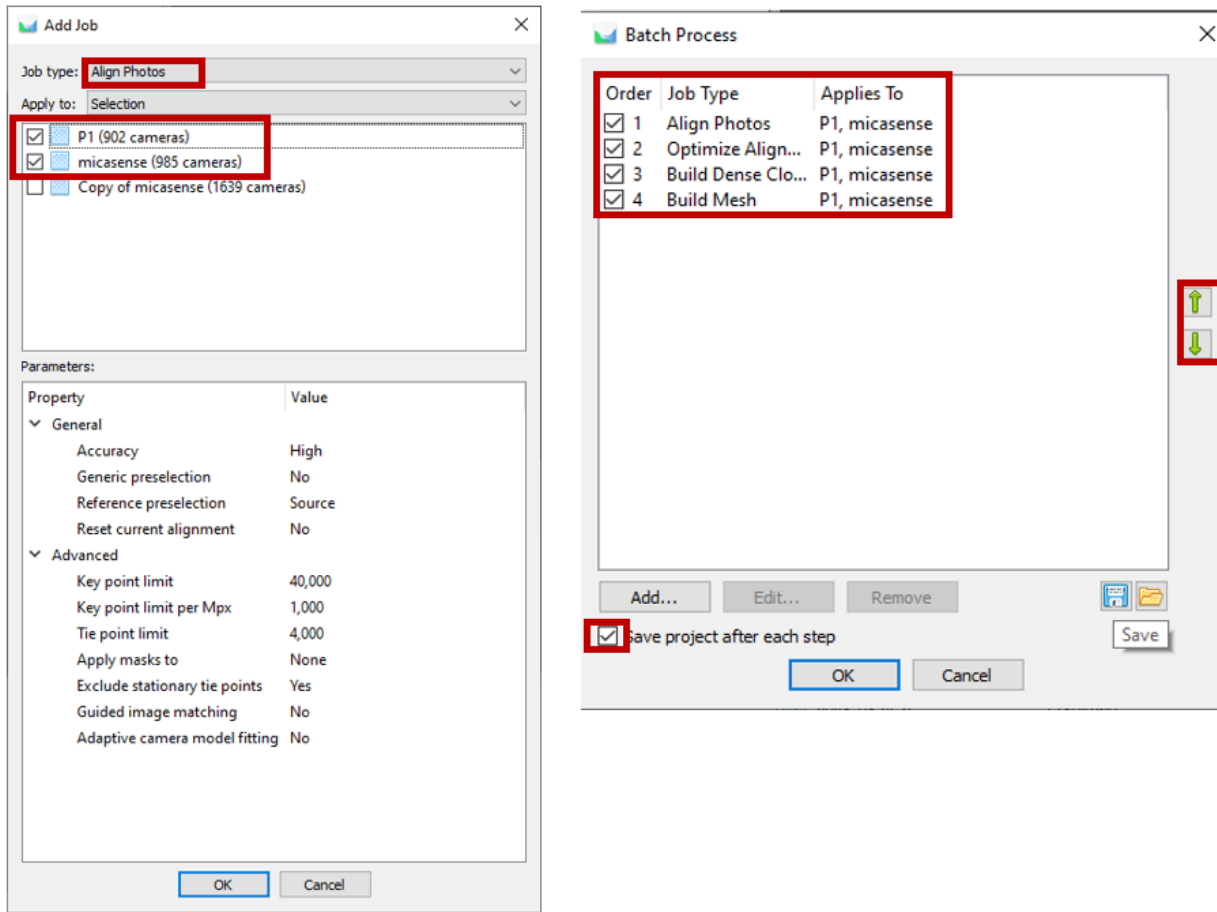


Figure 55: Add jobs, select chunks, and update parameters for each job. Select OK. Add more jobs as required. Select 'Save project after each step'. Click OK to start the jobs.

Appendix 5: Processing workflow using a custom Metashape window

This section describes another approach where a custom processing menu is used to run the same workflow. User input is still required to inspect and select calibration images, information on these steps is provided on-screen.

- Install package PySide2 in Metashape (see 'Install external packages')
- Copy metashape_proc_widget.py and upd_micasense_pos.py to C:\Users\\AppData\Local\Agisoft\Metashape Pro\scripts\
- Open Agisoft Metashape Pro. Switch to the 'Console' tab to view progress of the script.
- A custom option 'Metashape processing menu' would appear on the toolbar. Click on it to open the 'Metashape processing' window. **There are four steps to complete** as shown in Figure 56. These steps are described in the rest of this section.

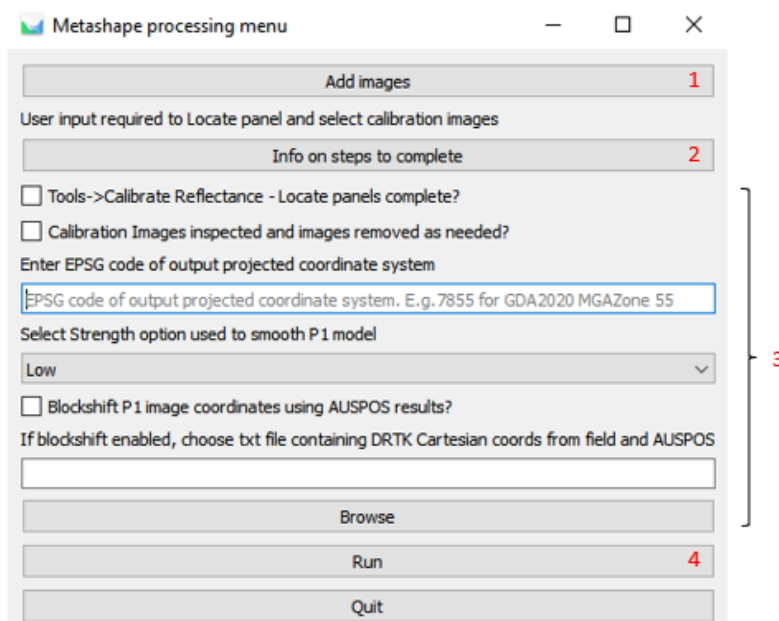
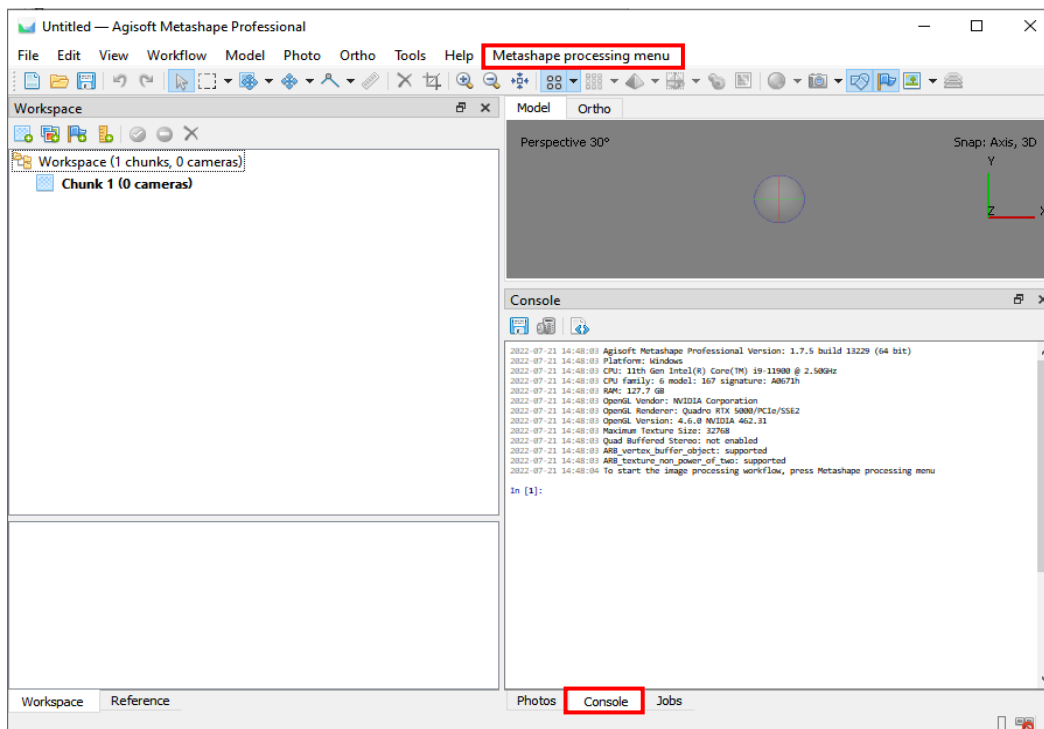


Figure 56: 'Metashape processing menu' appears on the toolbar when Metashape Pro is opened. The four steps in the workflow are shown above.

Add images

1. Click on Add images in the custom window. In the dialog that opens, click on 'Create chunks'. Select the folder where the rgb/ and multispec/ folders are located. This will create chunks rgb and multispec and add the images. The progress dialog displays the overall progress.

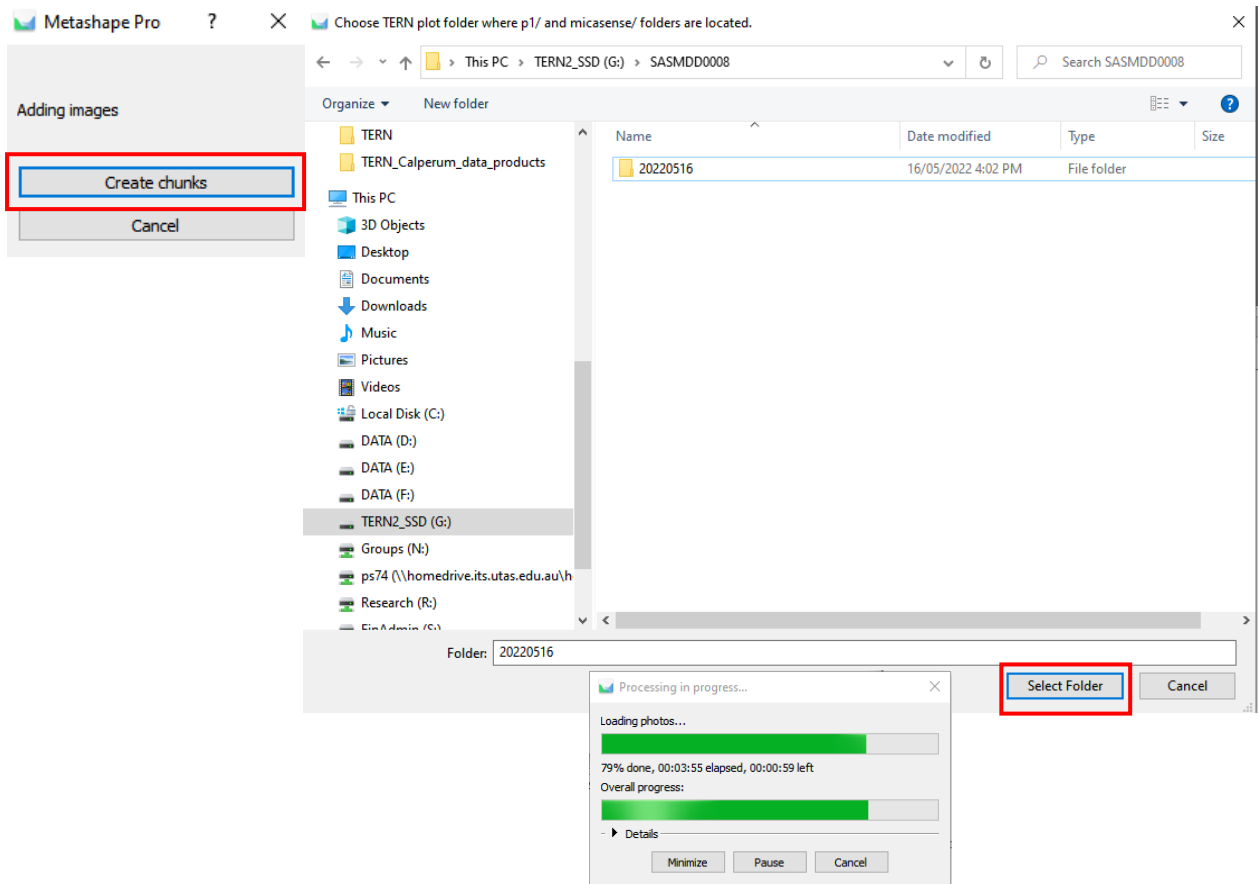


Figure 57: Step 1: 'Add Images' and select the folder with the p1/ and micasense folders

When all the images have been added, a dialog appears to 'Specify the project name' (default location of imagery/metashape in the plot folder). Enter a name in the format YYYYMMDD_PlotName.psx (YYYYMMDD is the date of data collection) and click Save.

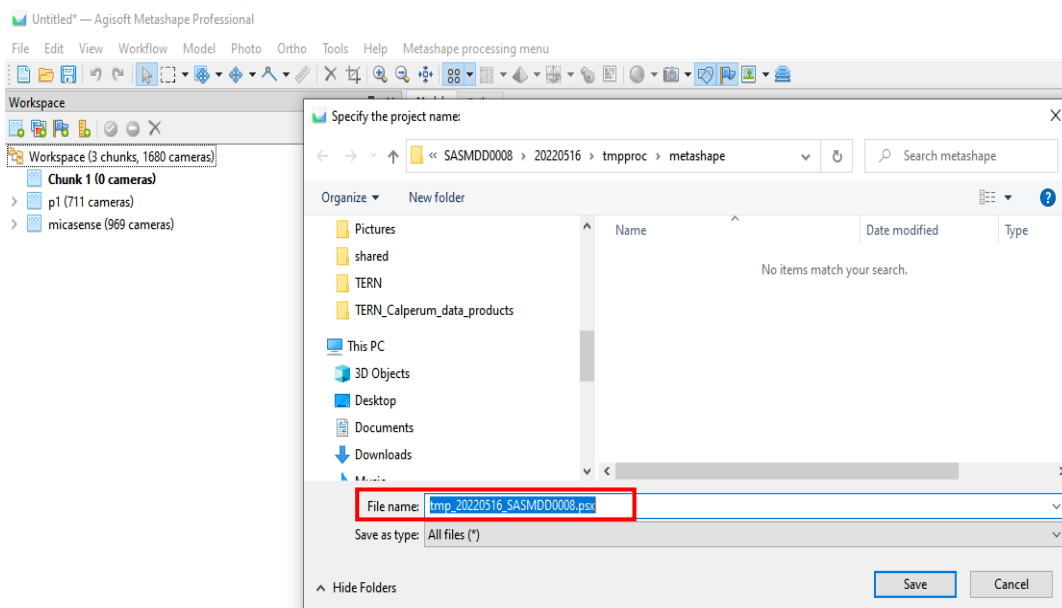


Figure 58: After the images have been added, when prompted enter a name for the Metashape project.

Select calibration images

- The next step requires user input to select the calibration images for micasense reflectance calibration. In the Metashape processing window, click on 'Info on steps to complete'. Complete Steps 1 to 3 listed. **Note that this window can be left open while the steps are completed using the Metashape toolbar.** (For screenshots of these steps, refer to MicaSense reflectance calibration.) Select OK when done.

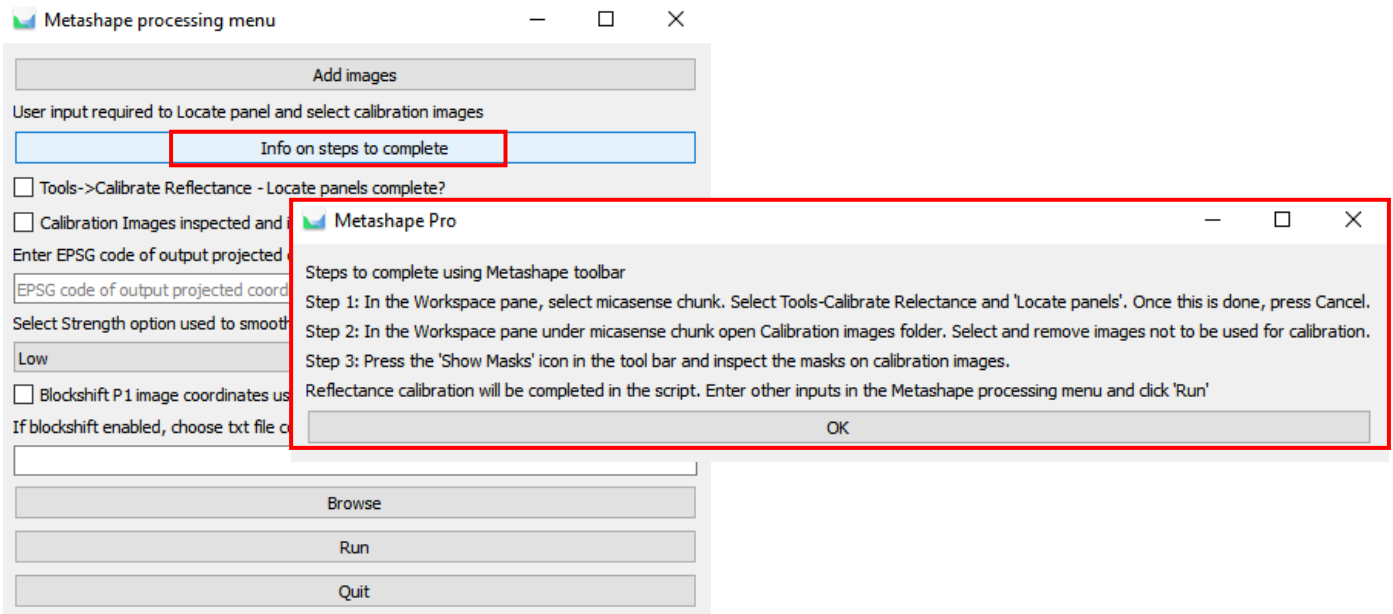


Figure 59: Step 2: Follow onscreen information to Locate panel and select calibration images.

Run the processing workflow

- Check both the buttons to mark the steps complete. Enter the EPSG code of the output projected CRS. Select Strength value to be used to smooth the P1 3D model. If blockshift of P1 images is necessary, select the option and browse to select the txt file containing the cartesian coordinates from the field and AUSPOS (See Process D-RTK2 base station data).
- Select Run.

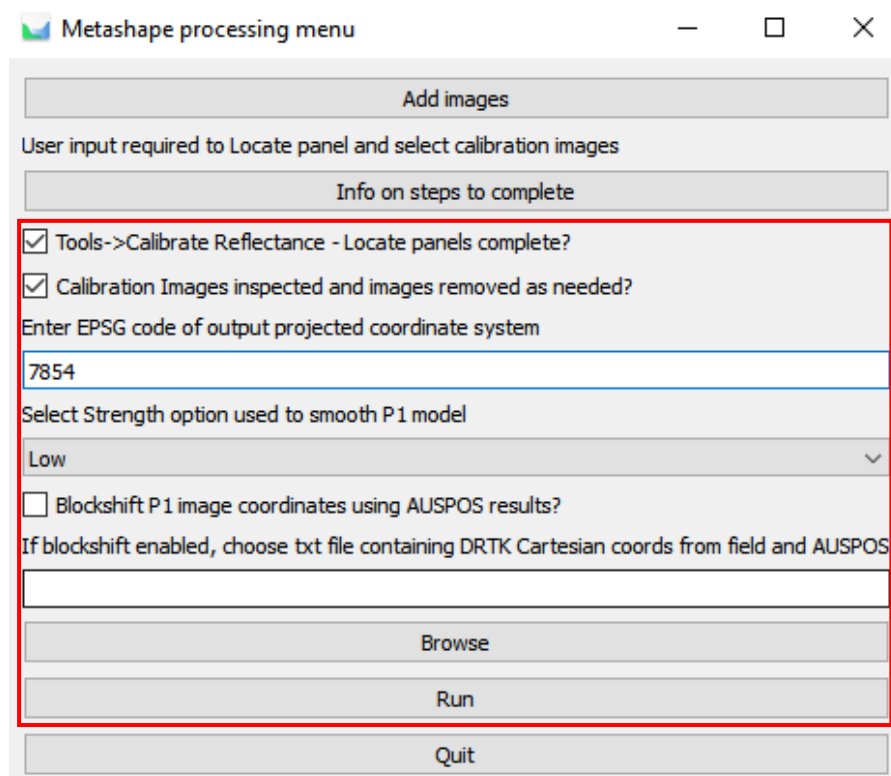


Figure 60: Enter the EPSG code for the projected target CRS, select a smoothing strength for the P1 3D model. Click Run to start the workflow.

5. Progress will be displayed on the Metashape progress dialog. When processing is complete, the RGB and multispectral orthomosaic tif are saved in the <sensor>/level1_proc/ folders. Intermediate files are saved in the project folder.
6. In case of any errors in the workflow, the log file (selected in Agisoft Metashape) and the Console tab will have details on the error and processing step that it appeared on. To fix the error and restart processing using the Metashape GUI, refer to 'Summary of processing workflow using Agisoft Metashape' for equivalent Metashape Toolbar commands. To restart the workflow using a Batch Process refer to 'Appendix 4: Metashape Batch Process'.

Revision History

Date	Revision	Changes
24/09/2021	1.0	Initial version
04/11/2021	1.1	Updated after review by Darren
15/11/2021	1.2	Updated after Oval trial flight
18/11/2021	1.3	Formatting updates
09/02/2022	1.4	Updates following review by Shaun Levick
12/05/2022	1.5	Update to D-RTK 2 processing when base station battery was changed. Highlight that MRK files must be copied to a path when more than 1 flight. Specified GPS/INS fields in Summary table.
02/08/2022	2.0	Updates following Calperum campaign in May 2022
03/11/2022	3.0	Updates following reviews from team